



华中科技大学
Huazhong University of
Science and Technology

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《电力系统分析》(I)

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第四章 电力网络的数学模型

4-1 节点导纳矩阵

4-2 网络方程的解法

4-3 节点阻抗矩阵

4-4 节点编号顺序的优化

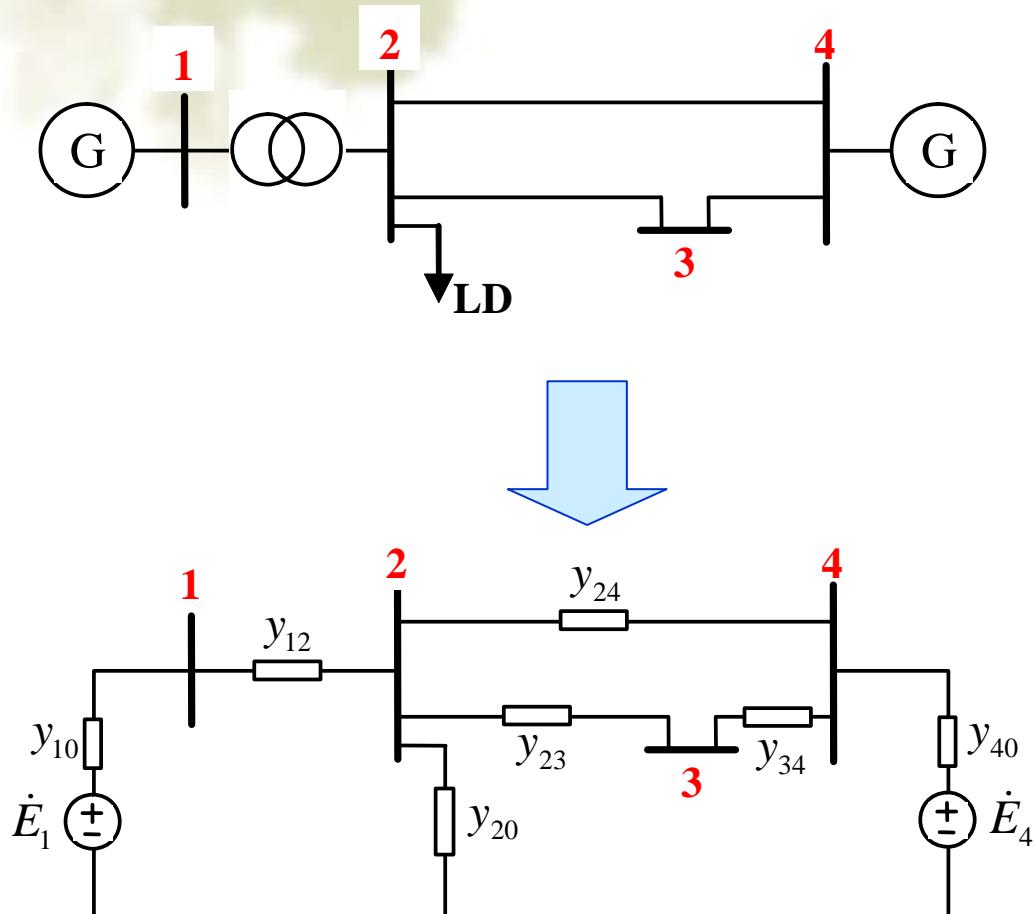
第四章 电力网络的数学模型

4.1 节点导纳矩阵

1. 用于短路计算的电力系统数学模型
2. 节点方程
3. 节点导纳矩阵元素的物理意义
4. Y 阵的修改（网络结构变化、故障等）

4-1 节点导纳矩阵

1. 用于短路计算的电力系统数学模型



- ❖ 发电机：电势源支路
- ❖ 电力网络：一相等值电路，略去变压器励磁支路和线路电容
- ❖ 负荷：恒定阻抗
- ❖ 零电位参考节点不予编号

4-1 节点导纳矩阵

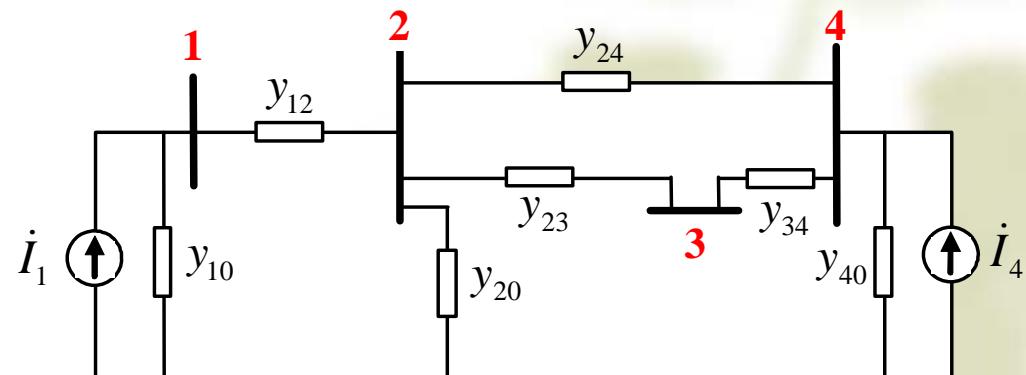
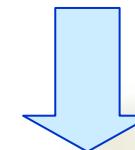
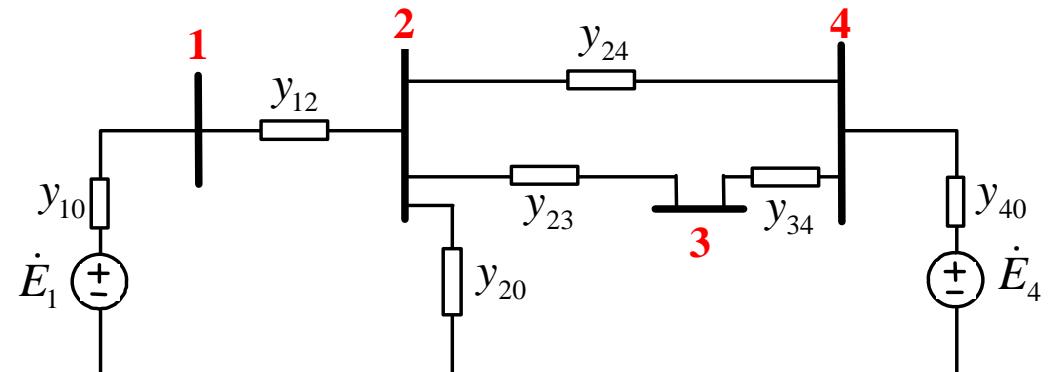
2. 节点方程

电势源支路转换

为电流源支路，

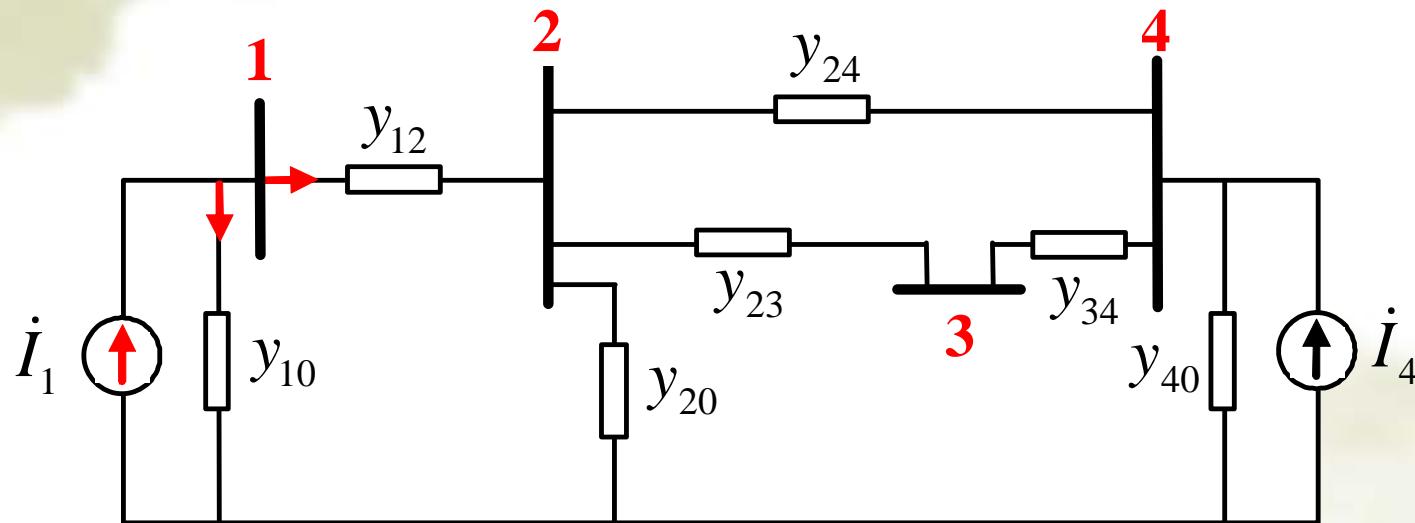
根据KCL定律列

写每一个节点的
电流方程式。



4-1 节点导纳矩阵

2. 节点方程—节点1

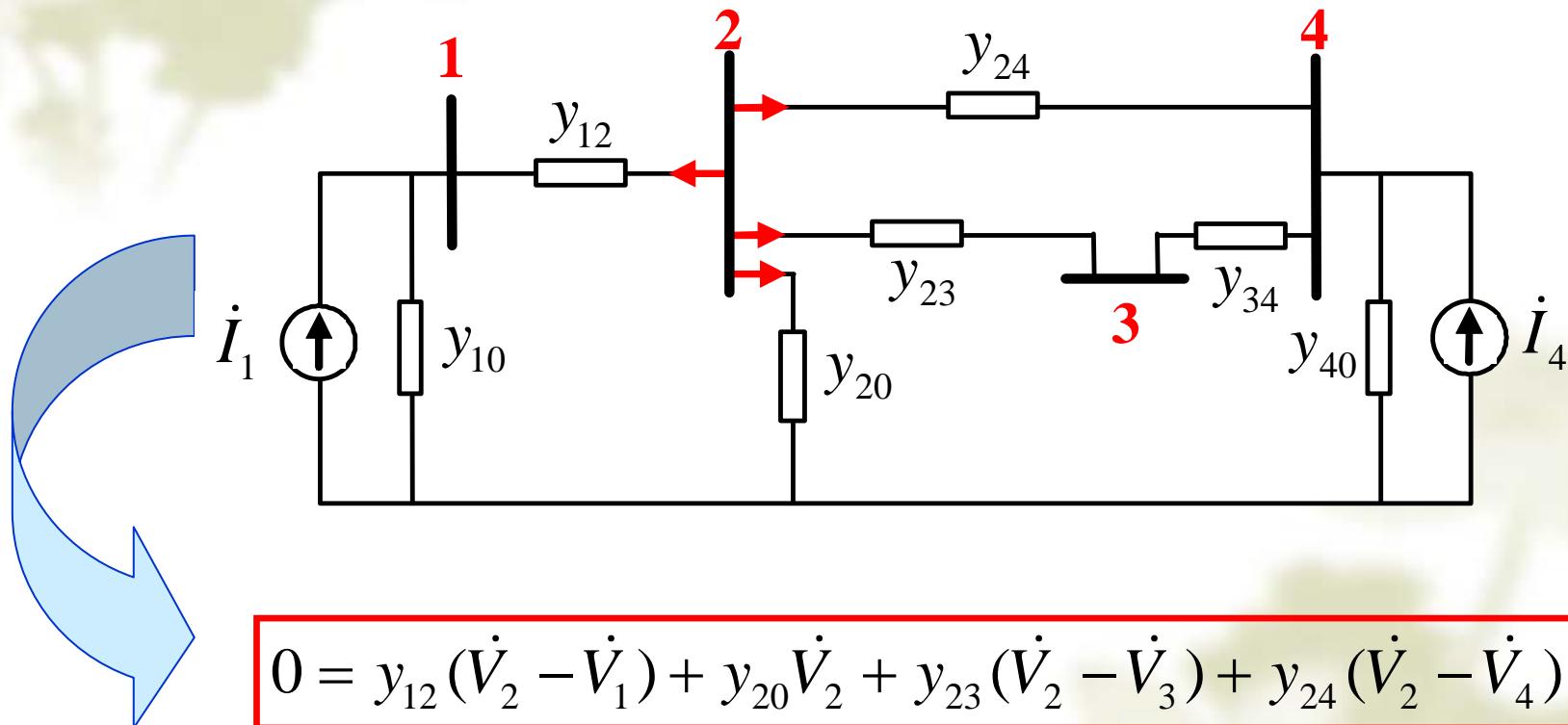


$$\dot{I}_1 = y_{10}\dot{V}_1 + y_{12}(\dot{V}_1 - \dot{V}_2)$$

$$\dot{I}_1 = (y_{10} + y_{12})\dot{V}_1 - y_{12}\dot{V}_2$$

4-1 节点导纳矩阵

2. 节点方程—节点2

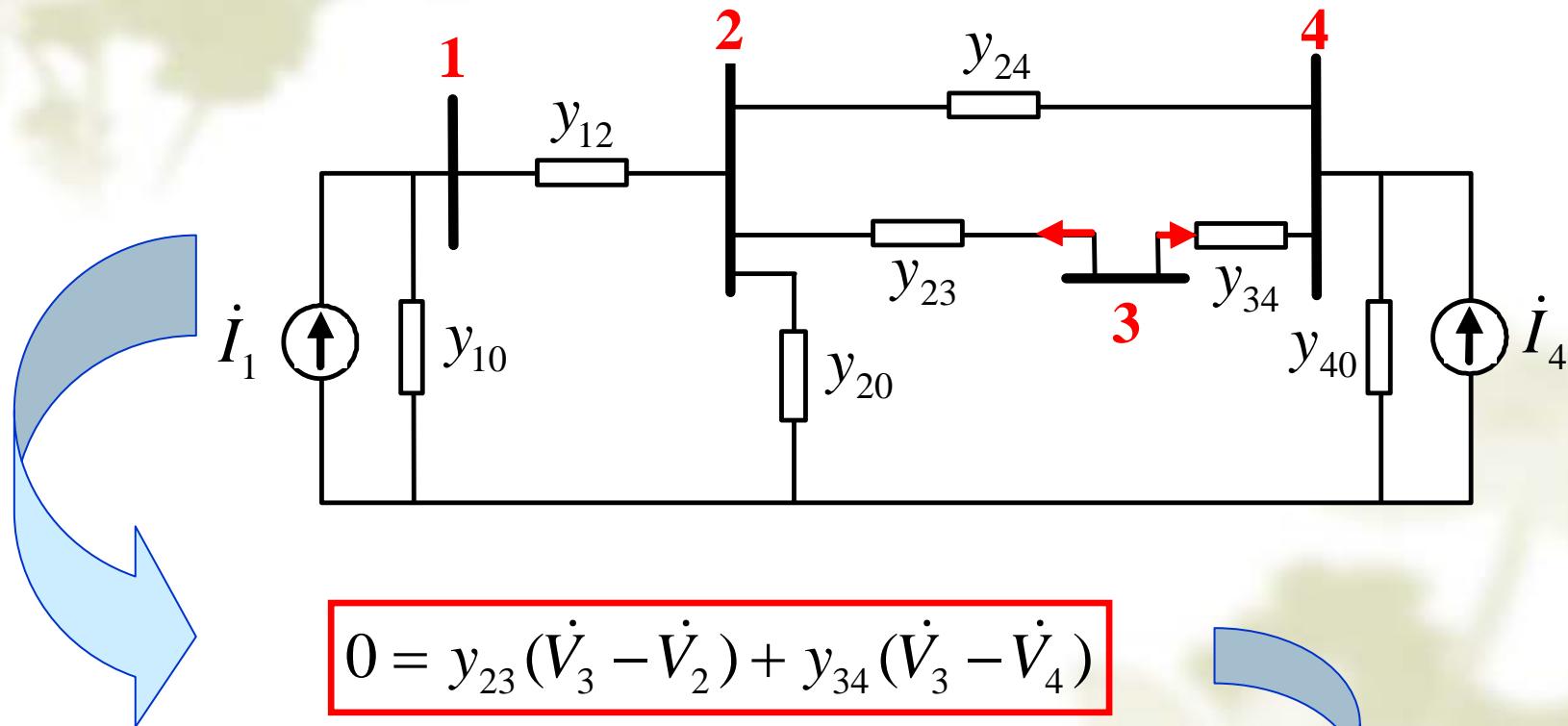


$$0 = y_{12}(\dot{V}_2 - \dot{V}_1) + y_{20}\dot{V}_2 + y_{23}(\dot{V}_2 - \dot{V}_3) + y_{24}(\dot{V}_2 - \dot{V}_4)$$

$$0 = -y_{12}\dot{V}_1 + (y_{12} + y_{20} + y_{23} + y_{24})\dot{V}_2 - y_{23}\dot{V}_3 - y_{24}\dot{V}_4$$

4-1 节点导纳矩阵

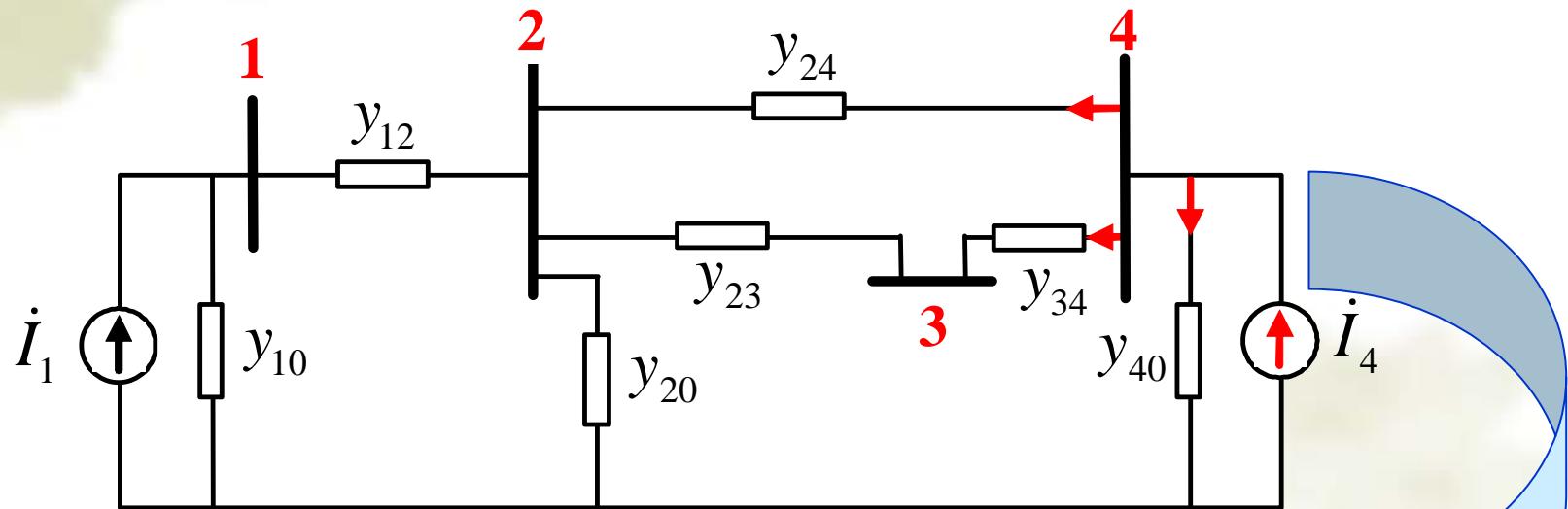
2. 节点方程—节点3



$$0 = -y_{23}\dot{V}_2 + (y_{23} + y_{34})\dot{V}_3 - y_{34}\dot{V}_4$$

4-1 节点导纳矩阵

2. 节点方程—节点4



$$\dot{I}_4 = y_{24}(\dot{V}_4 - \dot{V}_2) + y_{34}(\dot{V}_4 - \dot{V}_3) + y_{40}\dot{V}_4$$

$$\dot{I}_4 = -y_{24}\dot{V}_2 - y_{34}\dot{V}_3 + (y_{24} + y_{34} + y_{40})\dot{V}_4$$

4-1 节点导纳矩阵

2. 节点方程的矩阵形式

$$\begin{cases} \dot{I}_1 = (y_{10} + y_{12})\dot{V}_1 - y_{12}\dot{V}_2 \\ 0 = -y_{12}\dot{V}_1 + (y_{12} + y_{20} + y_{23} + y_{24})\dot{V}_2 - y_{23}\dot{V}_3 - y_{24}\dot{V}_4 \\ 0 = -y_{23}\dot{V}_3 + (y_{23} + y_{34})\dot{V}_3 - y_{34}\dot{V}_4 \\ \dot{I}_4 = -y_{24}\dot{V}_2 - y_{34}\dot{V}_3 + (y_{24} + y_{34} + y_{40})\dot{V}_4 \end{cases}$$

$$\begin{aligned} Y_{12} &= Y_{21} = -y_{12} \\ Y_{23} &= Y_{32} = -y_{23} \\ Y_{24} &= Y_{42} = -y_{24} \\ Y_{34} &= Y_{43} = -y_{34} \end{aligned}$$

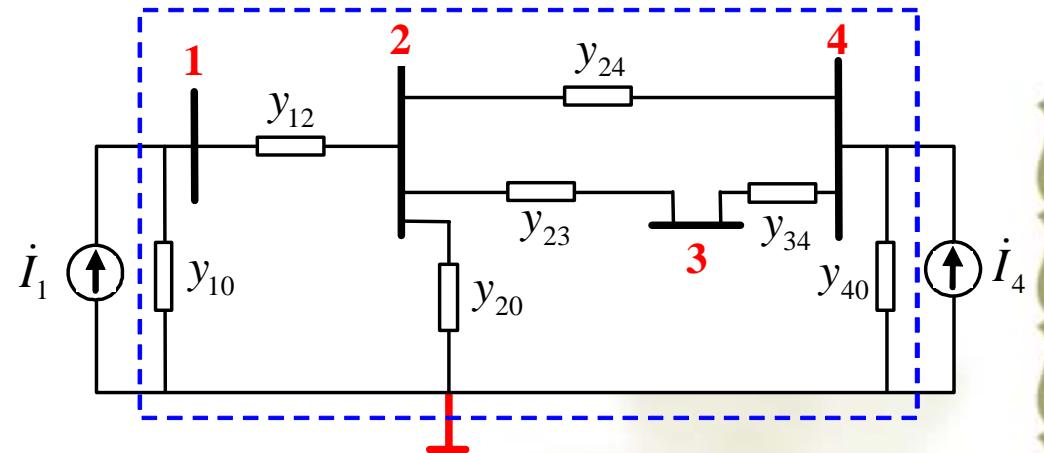
$$\begin{bmatrix} \dot{I}_1 \\ 0 \\ 0 \\ \dot{I}_4 \end{bmatrix} = \begin{bmatrix} Y_{11} & Y_{12} & 0 & 0 \\ Y_{21} & Y_{22} & Y_{23} & Y_{24} \\ 0 & Y_{32} & Y_{33} & Y_{34} \\ 0 & Y_{42} & Y_{43} & Y_{44} \end{bmatrix} \begin{bmatrix} \dot{V}_1 \\ \dot{V}_2 \\ \dot{V}_3 \\ \dot{V}_4 \end{bmatrix}$$

$$\begin{aligned} Y_{11} &= y_{10} + y_{12} \\ Y_{22} &= y_{12} + y_{20} + y_{23} + y_{24} \\ Y_{33} &= y_{23} + y_{34} \\ Y_{44} &= y_{24} + y_{34} + y_{40} \end{aligned}$$

4-1 节点导纳矩阵

2. 节点方程的矩阵形式

$$\begin{bmatrix} \dot{I}_1 \\ 0 \\ 0 \\ \dot{I}_4 \end{bmatrix} = \begin{bmatrix} Y_{11} & Y_{12} & 0 & 0 \\ Y_{21} & Y_{22} & Y_{23} & Y_{24} \\ 0 & Y_{32} & Y_{33} & Y_{34} \\ 0 & Y_{42} & Y_{43} & Y_{44} \end{bmatrix} \begin{bmatrix} \dot{V}_1 \\ \dot{V}_2 \\ \dot{V}_3 \\ \dot{V}_4 \end{bmatrix}$$



$$\begin{bmatrix} \dot{I}_1 \\ \dot{I}_2 \\ \dot{I}_3 \\ \dot{I}_4 \end{bmatrix} = \begin{bmatrix} Y_{11} & Y_{12} & Y_{13} & Y_{14} \\ Y_{21} & Y_{22} & Y_{23} & Y_{24} \\ Y_{31} & Y_{32} & Y_{33} & Y_{34} \\ Y_{41} & Y_{42} & Y_{43} & Y_{44} \end{bmatrix} \begin{bmatrix} \dot{V}_1 \\ \dot{V}_2 \\ \dot{V}_3 \\ \dot{V}_4 \end{bmatrix}$$

节点注入电流: $\dot{\mathbf{I}} = [\dot{I}_1 \quad \dot{I}_2 \quad \dot{I}_3 \quad \dot{I}_4]^T$

节点电压: $\dot{\mathbf{V}} = [\dot{V}_1 \quad \dot{V}_2 \quad \dot{V}_3 \quad \dot{V}_4]^T$

→ $\dot{\mathbf{I}} = \mathbf{Y}\dot{\mathbf{V}}$

4-1 节点导纳矩阵

2. 节点方程—n个独立节点的电力网络数学模型

$$\begin{bmatrix} \dot{I}_1 \\ \dot{I}_2 \\ \vdots \\ \dot{I}_n \end{bmatrix} = \begin{bmatrix} Y_{11} & Y_{12} & \cdots & Y_{1n} \\ Y_{21} & Y_{22} & \cdots & Y_{2n} \\ \vdots & \vdots & & \vdots \\ Y_{n1} & Y_{n2} & \cdots & Y_{nn} \end{bmatrix} \begin{bmatrix} \dot{V}_1 \\ \dot{V}_2 \\ \vdots \\ \dot{V}_n \end{bmatrix}$$

线性代数方程

$$\dot{\mathbf{I}} = \mathbf{Y} \dot{\mathbf{V}}$$

$$Y_{ii}$$

节点*i*自导纳

$$Y_{ij}$$

节点*ij*间互导纳

节点导纳矩阵

$$\mathbf{Y}$$

4-1 节点导纳矩阵

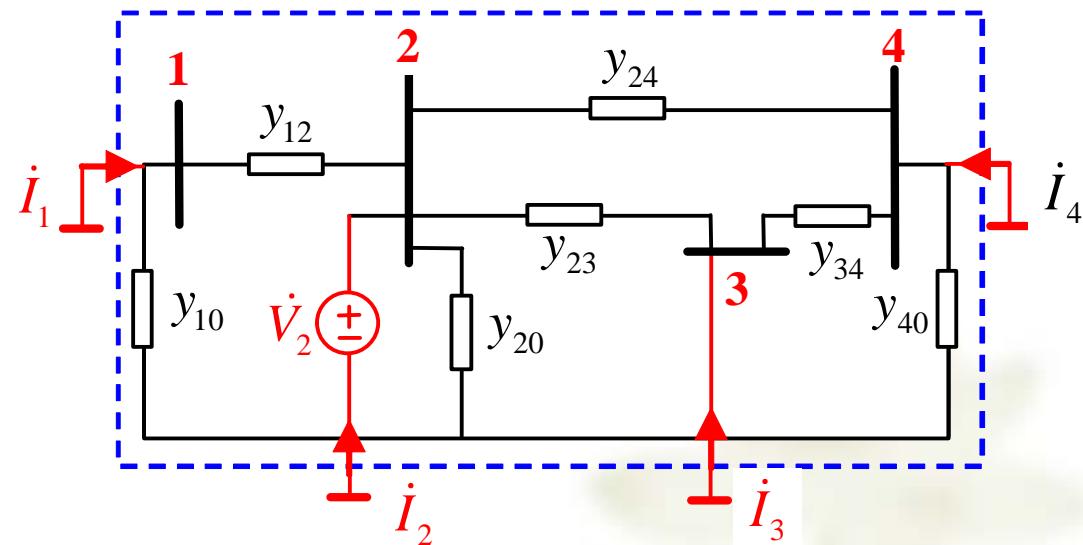
3. 节点导纳矩阵元素的物理意义

$$\dot{\mathbf{I}} = \mathbf{Y} \dot{\mathbf{V}}$$

$$\begin{aligned}\dot{V}_i &\neq 0, \\ \dot{V}_j &= 0, \\ (j &\neq i)\end{aligned}$$

$$\left\{ \begin{array}{l} \dot{I}_i = \sum_{j=1}^n Y_{ij} \dot{V}_j \\ \dot{I}_j = \sum_k Y_{jk} \dot{V}_k \end{array} \right.$$

$$\begin{aligned}\dot{I}_i &= Y_{ii} \dot{V}_i \rightarrow Y_{ii} = \dot{I}_i / \dot{V}_i \\ \dot{I}_j &= Y_{ji} \dot{V}_i \rightarrow Y_{ji} = \dot{I}_j / \dot{V}_i\end{aligned}$$

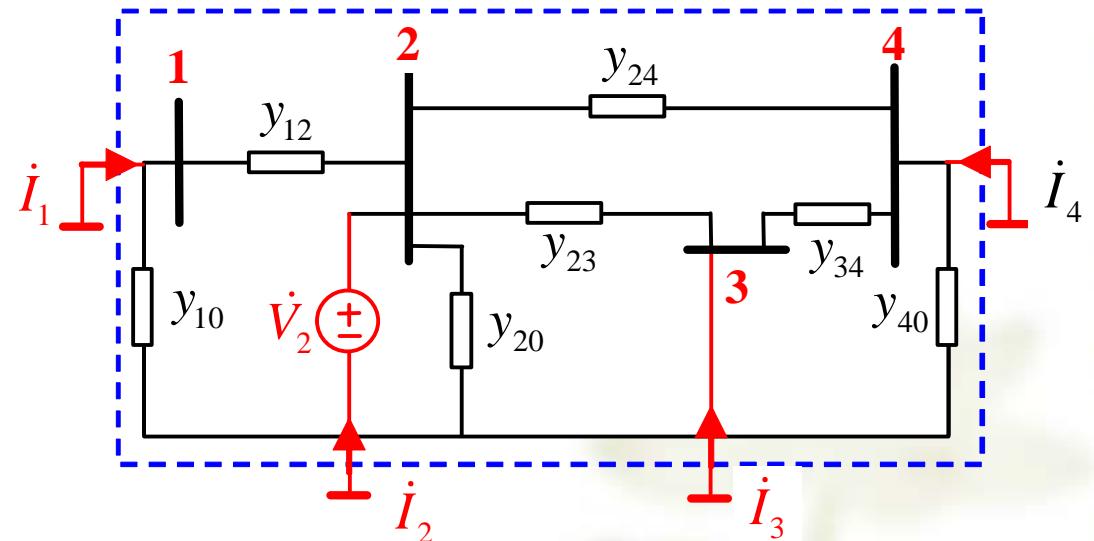


$$\begin{aligned}Y_{22} &= \dot{I}_2 / \dot{V}_2 = y_{20} + y_{12} + y_{23} + y_{24} \\ Y_{12} &= \dot{I}_1 / \dot{V}_2 = -y_{12}, \quad Y_{32} = \dot{I}_3 / \dot{V}_2 = -y_{23} \\ Y_{42} &= \dot{I}_4 / \dot{V}_2 = -y_{24}\end{aligned}$$

4-1 节点导纳矩阵

3. 节点导纳矩阵元素的物理意义—自导纳

Y_{ii} : 当网络中除节点 i 以外所有节点都接地时, 从节点 i 注入网络的电流同施加于节点 i 的电压之比



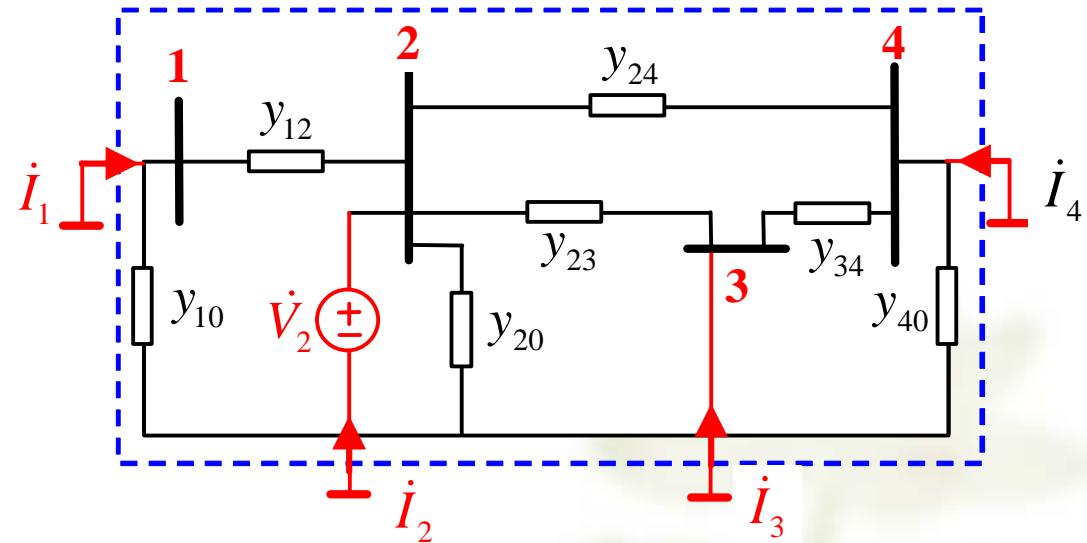
Y_{ii} : 与节点 i 相连的所有支路导纳之和

$$Y_{22} = \dot{I}_2 / \dot{V}_2 = y_{20} + y_{12} + y_{23} + y_{24}$$

4-1 节点导纳矩阵

3. 节点导纳矩阵元素的物理意义—互导纳

Y_{ji} : 当网络中除节点 i 以外所有节点都接地时, 从节点 j 注入网络的电流同施加于节点 i 的电压之比



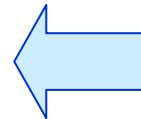
节点 j 的电流实际上是自网络流出并进入地中的电流, 所以 Y_{jk} 应等于节点 j 、 i 之间连接支路导纳的负值

$$Y_{12} = \dot{I}_1 / \dot{V}_2 = -y_{12}$$
$$Y_{32} = \dot{I}_3 / \dot{V}_2 = -y_{23}$$
$$Y_{42} = \dot{I}_4 / \dot{V}_2 = -y_{24}$$

4-1 节点导纳矩阵

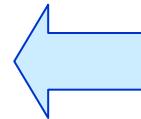
3. 节点导纳矩阵的特点

❖ 直观易求



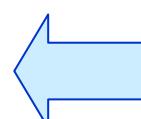
$$Y_{ii} = y_{i0} + \sum y_{ij}, \quad Y_{ij} = -\sum y_{ij}$$

❖ 对称矩阵



$$Y_{ij} = Y_{ji} = -\sum y_{ij}$$

❖ 稀疏矩阵



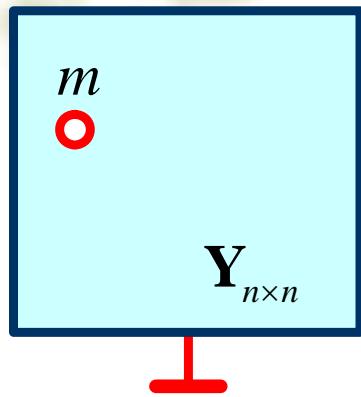
如果 ij 之间没有直接支路连接，则
 $Y_{ij} = Y_{ji} = 0$

$Y_{n \times n}$

❖ 设每个节点平均有 10 条出线，则节点导纳矩阵非零元素为 $11n$ 个，稀疏度 $11/n$

4-1 节点导纳矩阵

4. Y阵的修改—增加树支



$$\left[\begin{array}{cccc|c} Y_{11} & \cdots & Y_{1i} & \cdots & Y_{1n} & 0 \\ \vdots & \cdots & \vdots & \cdots & \vdots & \vdots \\ Y_{i1} & \cdots & Y_{ii} & \cdots & Y_{in} & Y_{ik} \\ \vdots & \cdots & \vdots & \cdots & \vdots & \vdots \\ Y_{n1} & \cdots & Y_{ni} & \cdots & Y_{nn} & 0 \\ \hline 0 & \cdots & Y_{ki} & \cdots & 0 & Y_{kk} \end{array} \right]$$

$$Y_{ii} = Y_{ii}^{(0)} + y_{ik}$$

$$Y_{kk} = y_{ik}$$

$$Y_{ik} = Y_{ki} = -y_{ik}$$

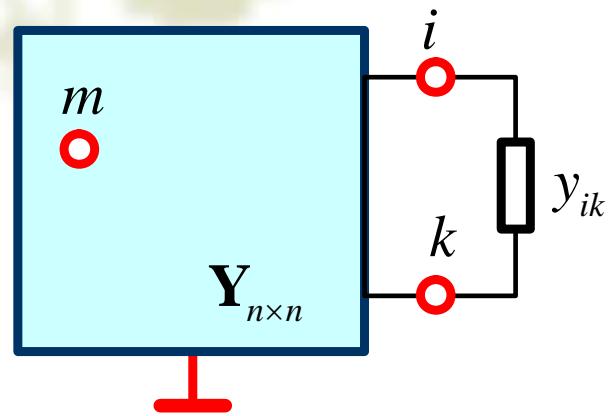
$$Y_{mk} = Y_{km} = 0$$

$$Y_{mi} = Y_{im} = Y_{im}^{(0)}$$

Y阵增加一行一列

4-1 节点导纳矩阵

4. Y阵的修改—增加连支



$$\begin{bmatrix} Y_{11} & \cdots & Y_{1i} & \cdots & Y_{1k} & \cdots & Y_{1n} \\ \vdots & \cdots & \vdots & \cdots & \vdots & \cdots & \vdots \\ Y_{i1} & \cdots & Y_{ii} & \cdots & Y_{ik} & \cdots & Y_{in} \\ \vdots & \cdots & \vdots & \cdots & \vdots & \cdots & \vdots \\ Y_{k1} & \cdots & Y_{ki} & \cdots & Y_{kk} & \cdots & Y_{kn} \\ \vdots & \cdots & \vdots & \cdots & \vdots & \cdots & \vdots \\ Y_{n1} & \cdots & Y_{ni} & v & Y_{nk} & \cdots & Y_{nn} \end{bmatrix}$$

Y阵阶数保持不变

$$Y_{ii} = Y_{ii}^{(0)} + y_{ik}$$

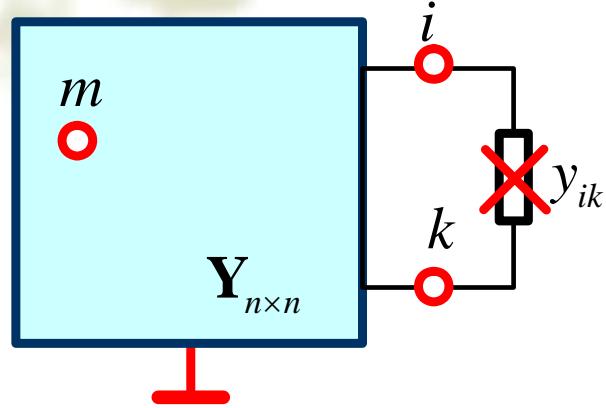
$$Y_{kk} = Y_{kk}^{(0)} + y_{ik}$$

$$Y_{ik} = Y_{ki} = Y_{ik}^{(0)} - y_{ik}$$

$$Y_{mk} = Y_{km} = Y_{mk}^{(0)}, \quad Y_{mi} = Y_{im} = Y_{im}^{(0)}$$

4-1 节点导纳矩阵

4. Y阵的修改——删除连支



$$\begin{bmatrix} Y_{11} & \cdots & Y_{1i} & \cdots & Y_{1k} & \cdots & Y_{1n} \\ \vdots & \cdots & \vdots & \cdots & \vdots & \cdots & \vdots \\ Y_{i1} & \cdots & Y_{ii} & \cdots & Y_{ik} & \cdots & Y_{in} \\ \vdots & \cdots & \vdots & \cdots & \vdots & \cdots & \vdots \\ Y_{k1} & \cdots & Y_{ki} & \cdots & Y_{kk} & \cdots & Y_{kn} \\ \vdots & \cdots & \vdots & \cdots & \vdots & \cdots & \vdots \\ Y_{n1} & \cdots & Y_{ni} & \cdots & Y_{nk} & \cdots & Y_{nn} \end{bmatrix}$$

Y阵阶数保持不变

$$Y_{ii} = Y^{(0)}_{ii} - y_{ik}$$

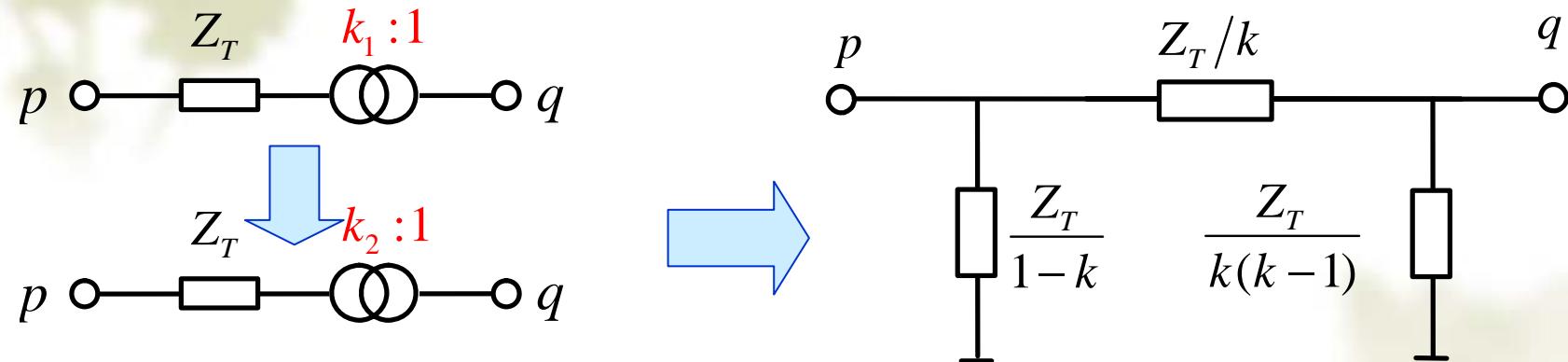
$$Y_{kk} = Y^{(0)}_{kk} - y_{ik}$$

$$Y_{ik} = Y_{ki} = Y^{(0)}_{ik} + y_{ik}$$

$$Y_{mk} = Y_{km} = Y^{(0)}_{mk}, \quad Y_{mi} = Y_{im} = Y^{(0)}_{im}$$

4-1 节点导纳矩阵

4. Y阵的修改—改变变压器变比



$$Y_{pp} = Y_{pp}^{(0)} - \Delta Y_{pp}^{(1)} + \Delta Y_{pp}^{(2)}$$

$$Y_{qq} = Y_{qq}^{(0)} - \Delta Y_{qq}^{(1)} + \Delta Y_{qq}^{(2)}$$

$$Y_{pq} = Y_{qp} = Y_{pq}^{(0)} - \Delta Y_{pq}^{(1)} + \Delta Y_{pq}^{(2)}$$

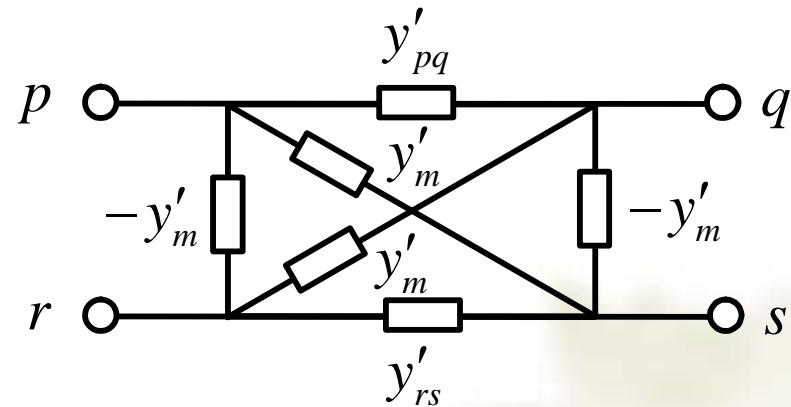
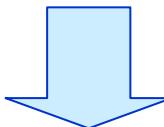
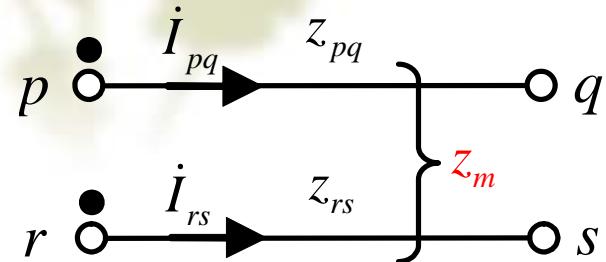
$$\Delta Y_{pp} = k/Z_T + (1-k)/Z_T = 1/Z_T$$

$$\Delta Y_{qq} = k/Z_T + k(k-1)/Z_T = k^2/Z_T$$

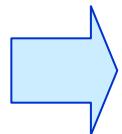
$$\Delta Y_{pq} = \Delta Y_{qp} = -k/Z_T$$

4-1 节点导纳矩阵

4. Y阵的修改—支路间存在互感



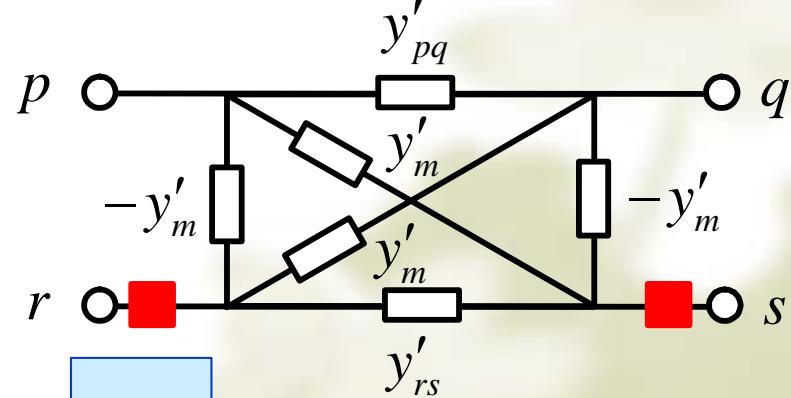
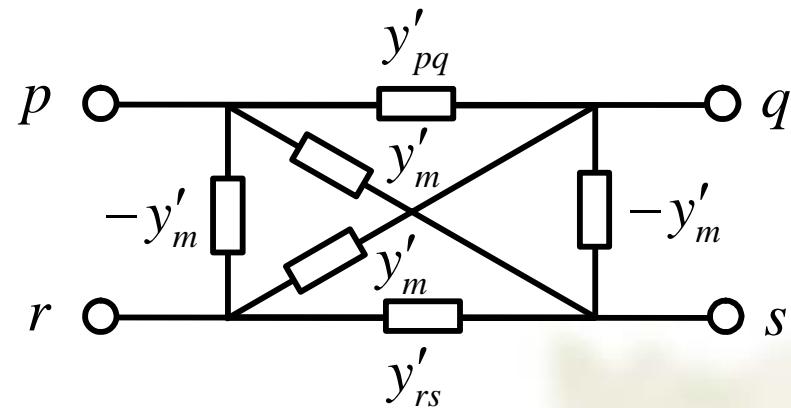
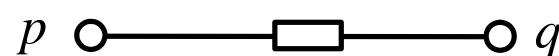
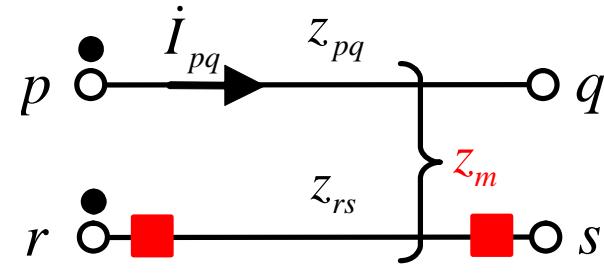
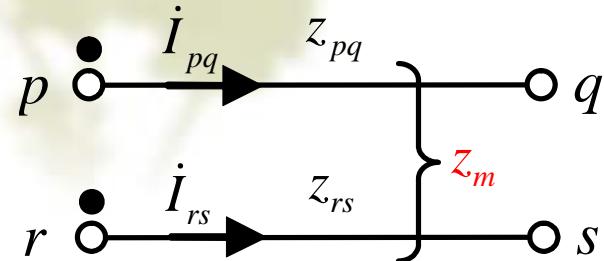
$$\begin{bmatrix} \dot{V}_p - \dot{V}_q \\ \dot{V}_r - \dot{V}_s \end{bmatrix} = \begin{bmatrix} z_{pq} & z_m \\ z_m & z_{rs} \end{bmatrix} \begin{bmatrix} \dot{I}_{pq} \\ \dot{I}_{rs} \end{bmatrix}$$



$$\begin{bmatrix} \dot{I}_{pq} \\ \dot{I}_{rs} \end{bmatrix} = \begin{bmatrix} y'_{pq} & y'_m \\ y'_m & y'_{rs} \end{bmatrix} \begin{bmatrix} \dot{V}_p - \dot{V}_q \\ \dot{V}_r - \dot{V}_s \end{bmatrix}$$

4-1 节点导纳矩阵

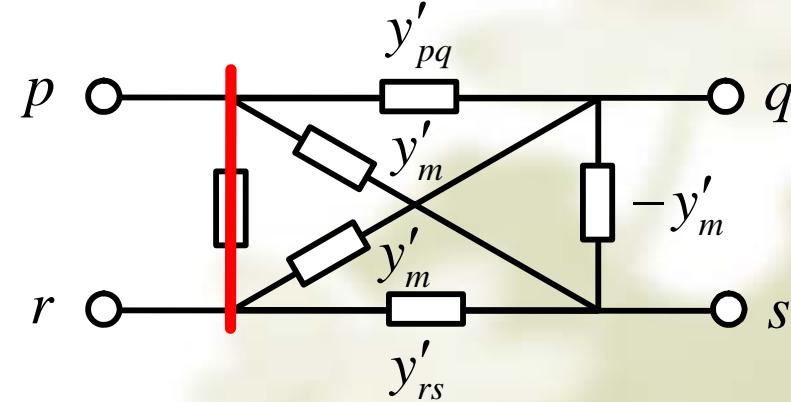
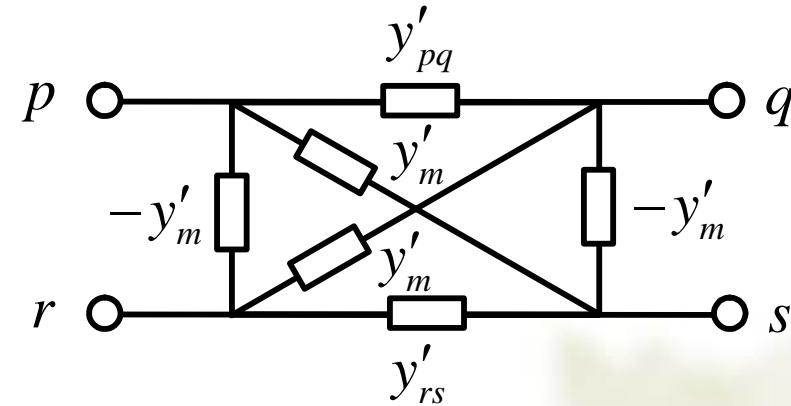
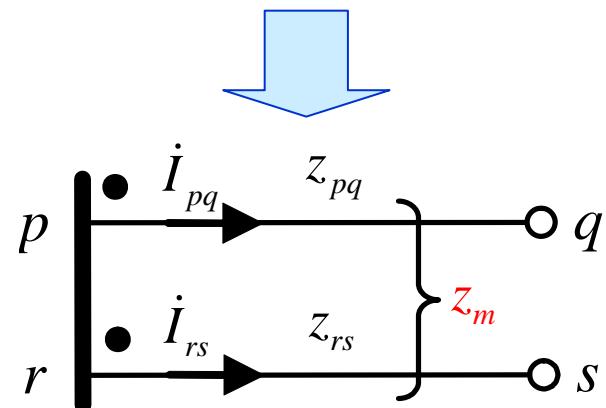
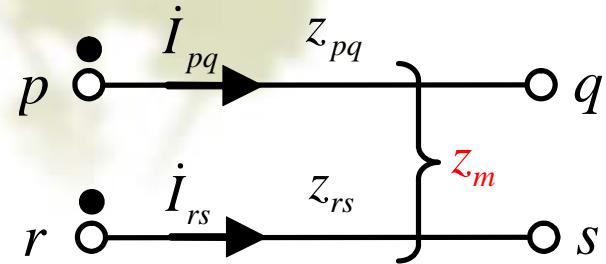
4. Y阵的修改—断开互感支路



EQU

4-1 节点导纳矩阵

4. Y阵的修改——一端互联的互感支路



4-3 节点阻抗矩阵

1. 节点阻抗矩阵

$$\begin{bmatrix} \dot{V}_1 \\ \dot{V}_2 \\ \vdots \\ \dot{V}_n \end{bmatrix} = \begin{bmatrix} Z_{11} & Z_{12} & \cdots & Z_{1n} \\ Z_{21} & Z_{22} & \cdots & Z_{2n} \\ \vdots & \vdots & \cdots & \vdots \\ Z_{n1} & Z_{n2} & \cdots & Z_{nn} \end{bmatrix} \begin{bmatrix} \dot{I}_1 \\ \dot{I}_2 \\ \vdots \\ \dot{I}_n \end{bmatrix}$$

$$\dot{\mathbf{I}} = \mathbf{Y} \dot{\mathbf{V}}$$

$$\dot{\mathbf{V}} = \mathbf{Z} \dot{\mathbf{I}}$$

$$Z_{ii}$$

节点*i*自阻抗

$$Z_{ij}$$

节点*ij*间互阻抗

节点阻
抗矩阵

$$\mathbf{Z} = \mathbf{Y}^{-1}$$

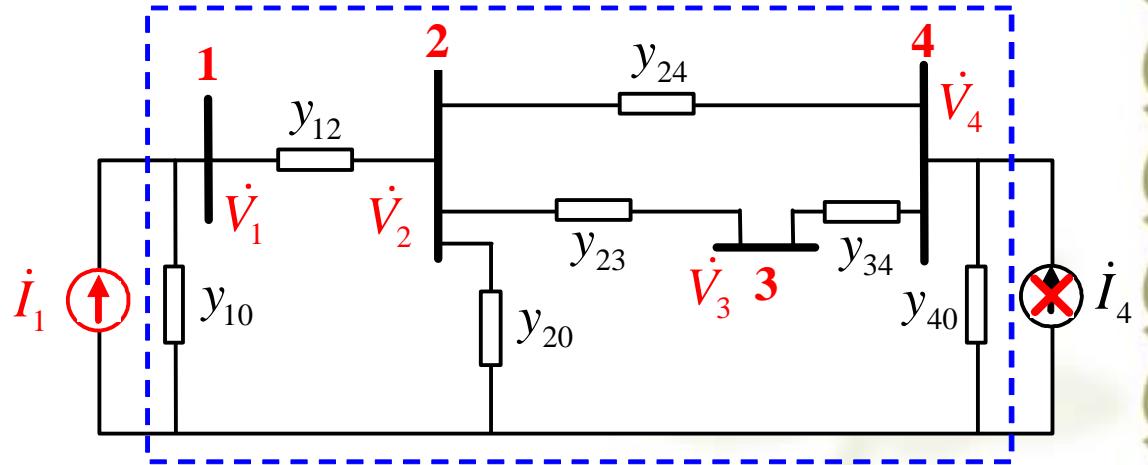
4-3 节点阻抗矩阵

2. 节点阻抗矩阵元素的物理意义

$$\dot{\mathbf{V}} = \mathbf{Z}\dot{\mathbf{I}}$$

$$\begin{aligned} \dot{I}_i &\neq 0, \\ \dot{I}_j &= 0, \\ (j &\neq i) \end{aligned}$$

$$\left\{ \begin{array}{l} \dot{V}_i = \sum_{j=1}^n Z_{ij} \dot{I}_j \\ \dot{V}_j = \sum_k Z_{jk} \dot{I}_k \end{array} \right.$$



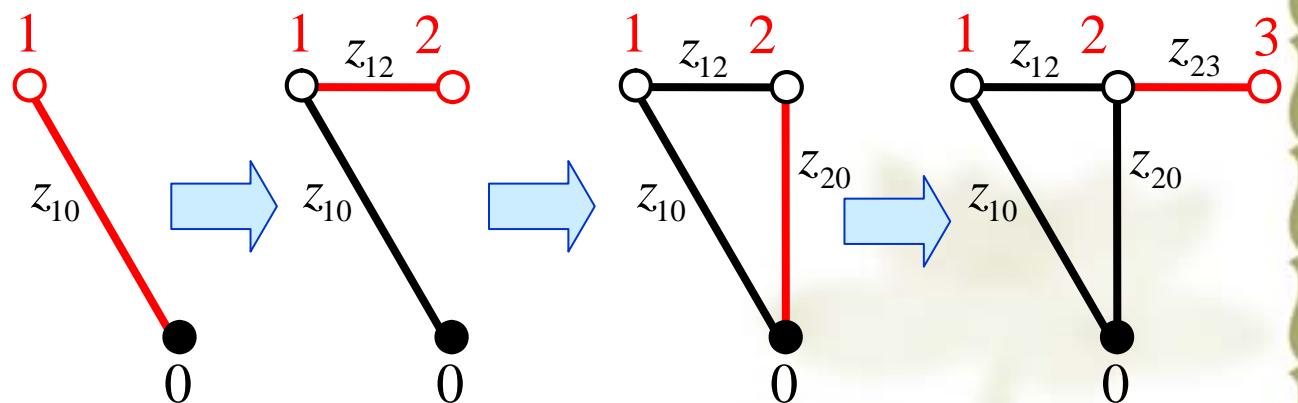
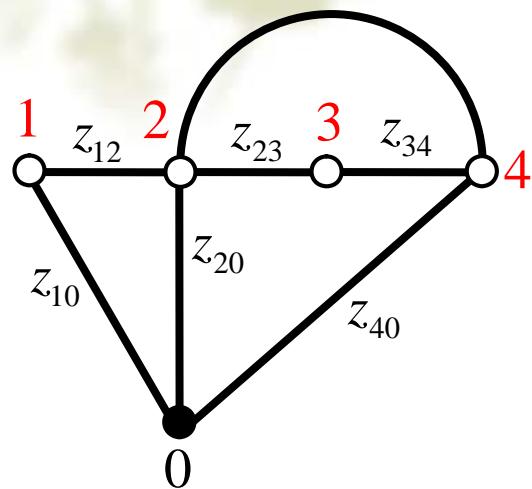
$$\begin{aligned} \dot{V}_i &= Z_{ii} \dot{I}_i \Rightarrow Z_{ii} = \dot{V}_i / \dot{I}_i \\ \dot{V}_j &= Z_{ji} \dot{I}_i \Rightarrow Z_{ji} = \dot{V}_j / \dot{I}_i \end{aligned}$$

❖ 对称矩阵
❖ 计算复杂

❖ 满阵

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-基本过程



$Z_{4 \times 4}$

$Z_{1 \times 1}$

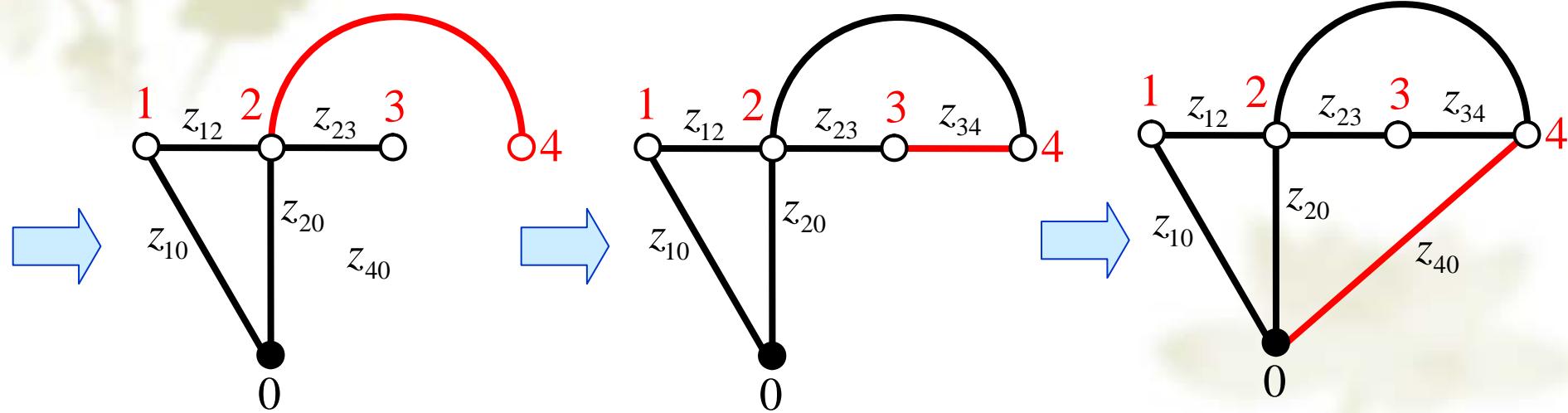
$Z_{2 \times 2}$

$Z'_{2 \times 2}$

$Z_{3 \times 3}$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-基本过程



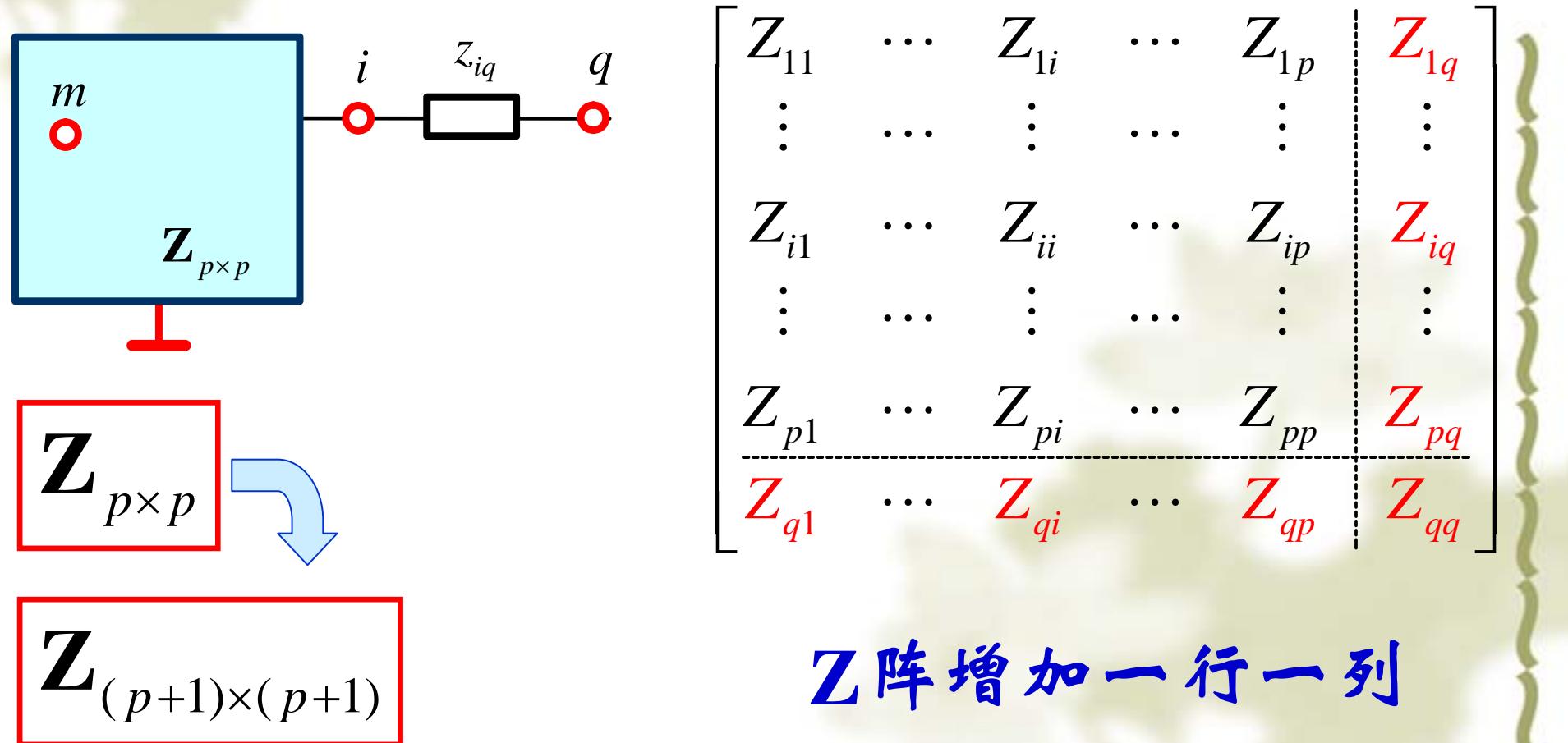
$$\mathbf{Z}'_{4 \times 4}$$

$$\mathbf{Z}''_{4 \times 4}$$

$$\mathbf{Z}_{4 \times 4}$$

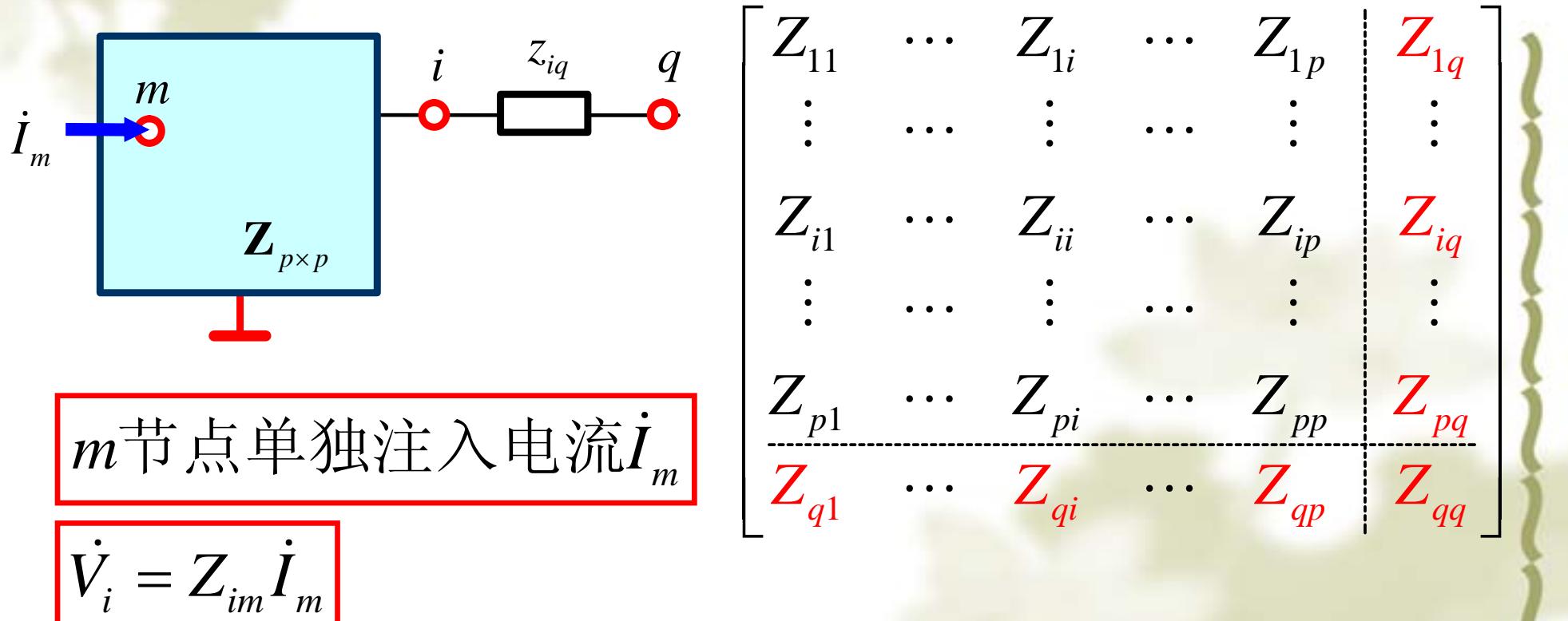
4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加树支



4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加树支



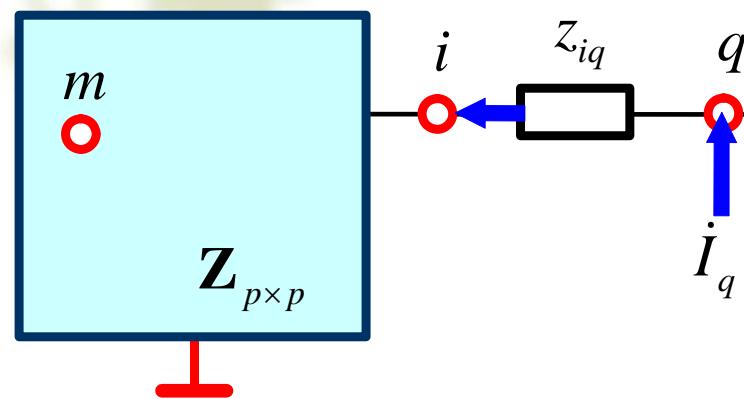
$$\dot{V}_i = Z_{im} \dot{I}_m$$

$$\dot{V}_q = Z_{qm} \dot{I}_m = \dot{V}_i = Z_{im} \dot{I}_m$$

$$Z_{qm} = Z_{im}$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加树支



q 节点单独注入电流 \dot{I}_q

$$\dot{V}_m = Z_{mq} \dot{I}_q = Z_{mi} \dot{I}_q$$

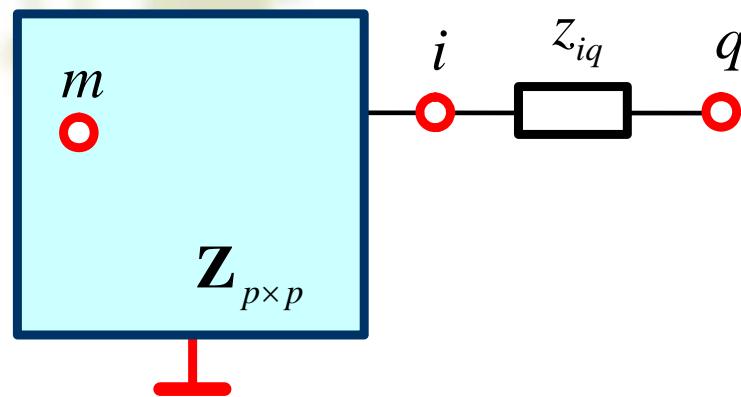
$$\dot{V}_q = \dot{V}_i + z_{iq} \dot{I}_q = (Z_{ii} + z_{iq}) \dot{I}_q = Z_{qq} \dot{I}_q$$

$$\left[\begin{array}{cccc|c} Z_{11} & \cdots & Z_{1i} & \cdots & Z_{1p} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z_{i1} & \cdots & Z_{ii} & \cdots & Z_{ip} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z_{p1} & \cdots & Z_{pi} & \cdots & Z_{pp} \\ \hline Z_{q1} & \cdots & Z_{qi} & \cdots & Z_{qp} \end{array} \right] \quad \left. \begin{array}{c} Z_{1q} \\ \vdots \\ Z_{iq} \\ \vdots \\ Z_{pq} \\ Z_{qq} \end{array} \right]$$

$$Z_{mq} = Z_{mi}$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加树支



Z阵增加一行一列

Z阵原有元素不变

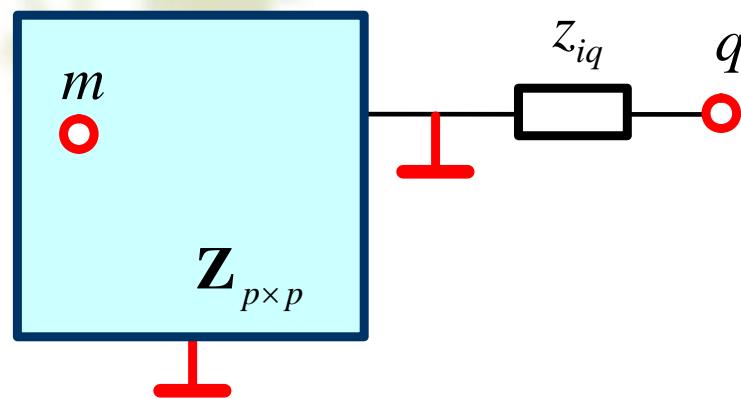
$$Z_{mq} = Z_{qm} = Z_{mi}, (m = 1, 2, \dots, p)$$

$$Z_{qq} = Z_{ii} + Z_{iq}$$

$$\left[\begin{array}{cccc|c} Z_{11} & \cdots & Z_{1i} & \cdots & Z_{1p} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z_{i1} & \cdots & Z_{ii} & \cdots & Z_{ip} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z_{p1} & \cdots & Z_{pi} & \cdots & Z_{pp} \\ \hline Z_{q1} & \cdots & Z_{qi} & \cdots & Z_{qp} \end{array} \right] \quad \left. \begin{array}{c} Z_{1q} \\ \vdots \\ Z_{iq} \\ \vdots \\ Z_{pq} \\ Z_{qq} \end{array} \right]$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加接地树支



Z阵增加一行一列

Z阵原有元素不变

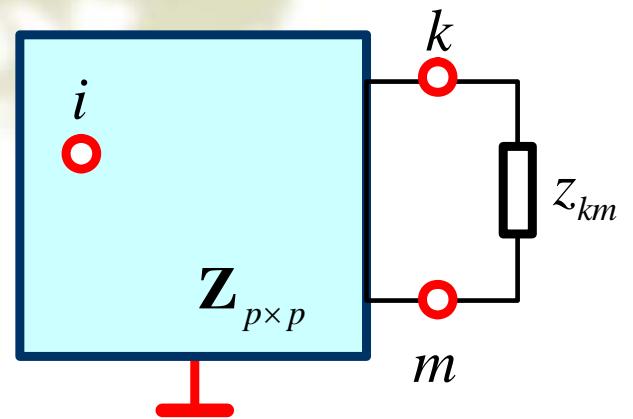
$$Z_{mq} = Z_{qm} = 0, (m = 1, 2, \dots, p)$$

$$Z_{qq} = z_{iq}$$

$$\left[\begin{array}{cccc|c} Z_{11} & \cdots & Z_{1i} & \cdots & Z_{1p} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z_{i1} & \cdots & Z_{ii} & \cdots & Z_{ip} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z_{p1} & \cdots & Z_{pi} & \cdots & Z_{pp} \\ \hline Z_{q1} & \cdots & Z_{qi} & \cdots & Z_{qp} \end{array} \right] \quad \left. \begin{array}{c} Z_{1q} \\ \vdots \\ Z_{iq} \\ \vdots \\ Z_{pq} \\ Z_{qq} \end{array} \right]$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加连支



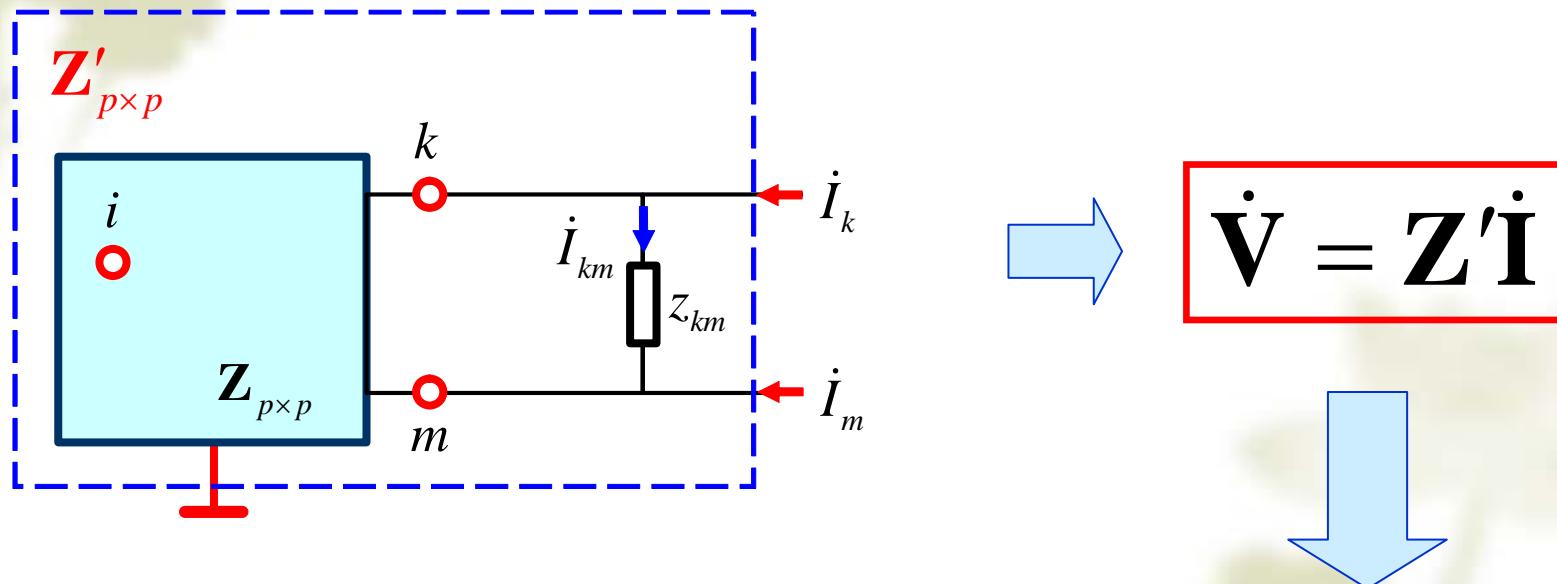
$Z_{p \times p} \rightarrow Z'_{p \times p}$

$$\begin{bmatrix} Z'_{11} & \cdots & Z'_{1m} & \cdots & Z'_{1k} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z'_{m1} & \cdots & Z'_{mm} & \cdots & Z'_{mk} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z'_{k1} & \cdots & Z'_{km} & \cdots & Z'_{kk} \\ \vdots & \cdots & \vdots & \cdots & \vdots \end{bmatrix}$$

z_{km} 支路会引起原网络电压电流分布的变化

4-3 节点阻抗矩阵

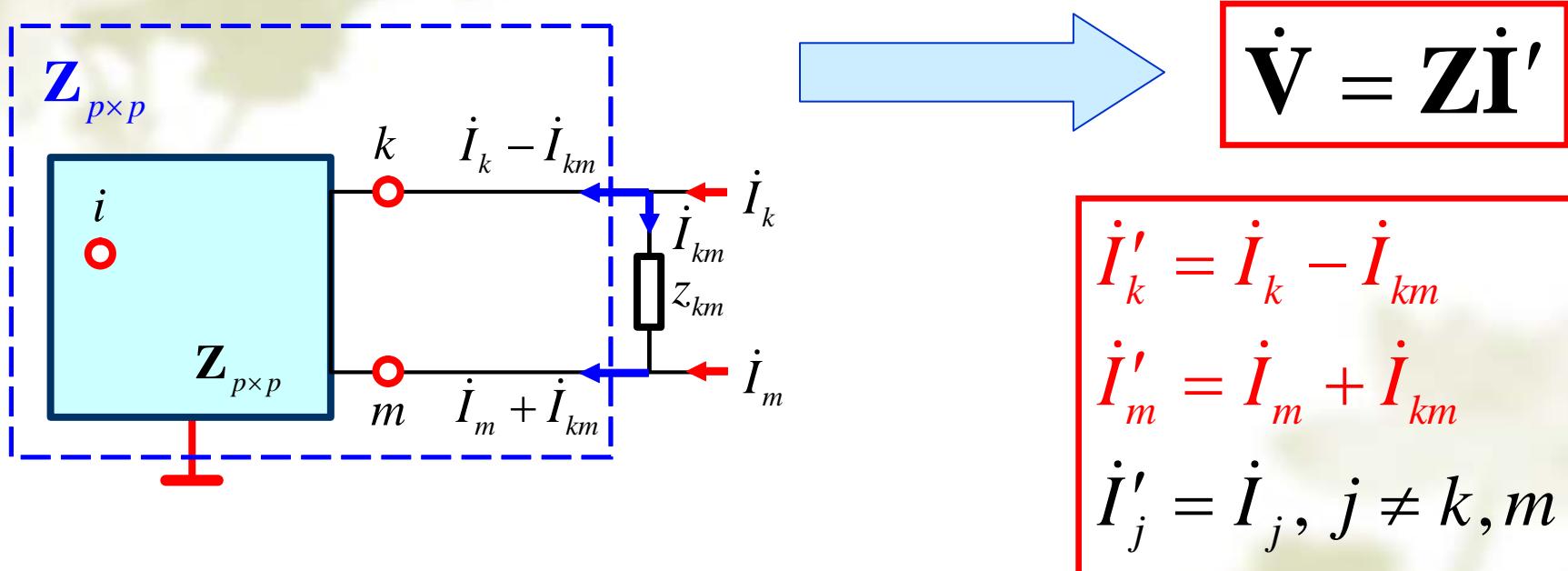
3. 支路追加法生成Z阵-追加连支



$$\dot{V}_i = \sum_{j=1}^p Z'_{ij} \dot{I}_j = Z'_{i1} \dot{I}_1 + \cdots + Z'_{ik} \dot{I}_k + \cdots + Z'_{im} \dot{I}_m + \cdots + Z'_{ip} \dot{I}_p$$

4-3 节点阻抗矩阵

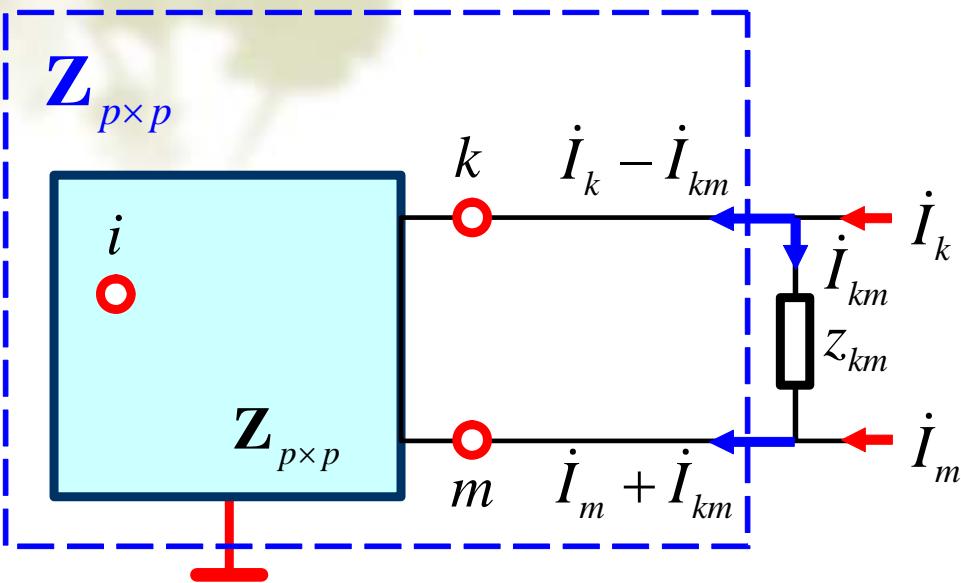
3. 支路追加法生成Z阵-追加连支



$$\dot{V}_i = \sum_{j=1}^p Z_{ij} \dot{I}'_j = Z_{i1} \dot{I}_1 + \cdots + Z_{ik} (\dot{I}_k - \dot{I}_{km}) + \cdots + Z_{im} (\dot{I}_m + \dot{I}_{km}) + \cdots + Z_{ip} \dot{I}_p$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加连支



$$\dot{V}_k = \sum_{j=1}^p Z_{kj} \dot{I}_j - (Z_{kk} - Z_{km}) \dot{I}_{km}$$

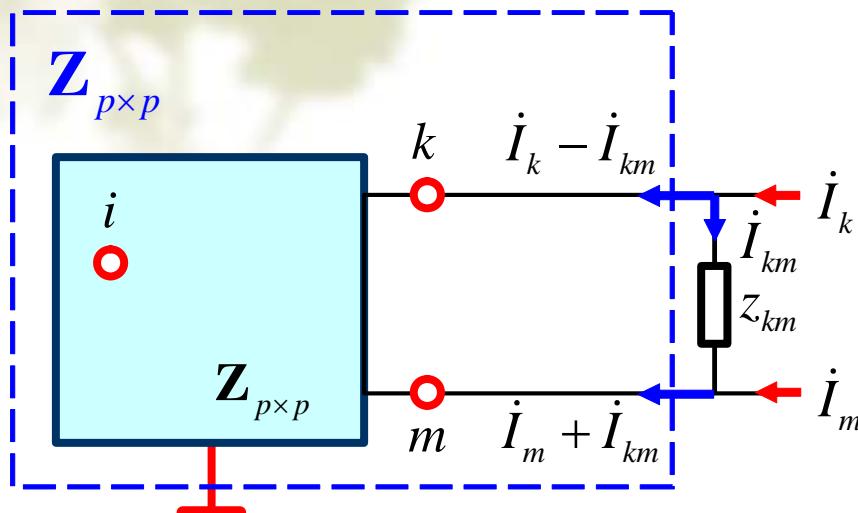
$$\dot{V}_m = \sum_{j=1}^p Z_{mj} \dot{I}_j - (Z_{mk} - Z_{mm}) \dot{I}_{km}$$

$$\dot{V}_i = \sum_{j=1}^p Z_{ij} \dot{I}_j - (Z_{ik} - Z_{im}) \dot{I}_{km}$$

$$\dot{V}_i = \sum_{j=1}^p Z_{ij} \dot{I}'_j = Z_{i1} \dot{I}'_1 + \cdots + Z_{ik} (\dot{I}_k - \dot{I}_{km}) + \cdots + Z_{im} (\dot{I}_m + \dot{I}_{km}) + \cdots + Z_{ip} \dot{I}_p$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加连支



$$\dot{V}_k = \sum_{j=1}^p Z_{kj} \dot{I}_j - (Z_{kk} - Z_{km}) \dot{I}_{km}$$

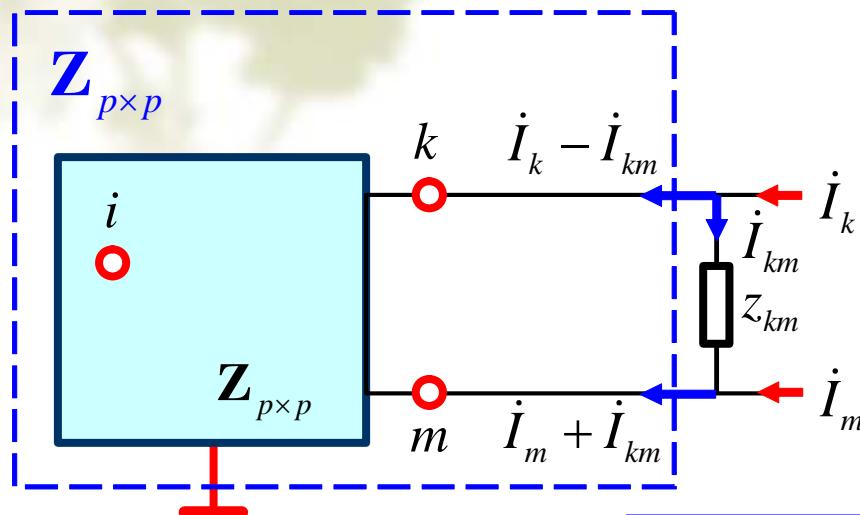
$$\dot{V}_m = \sum_{j=1}^p Z_{mj} \dot{I}_j - (Z_{mk} - Z_{mm}) \dot{I}_{km}$$

$$\dot{V}_k - \dot{V}_m = \sum_{j=1}^p (Z_{kj} - Z_{mj}) \dot{I}_j - (Z_{kk} - Z_{km} - Z_{mk} + Z_{mm}) \dot{I}_{km} = z_{km} \dot{I}_{km}$$

$$\dot{I}_{km} = \frac{1}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})} \sum_{j=1}^p (Z_{kj} - Z_{mj}) \dot{I}_j$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加连支



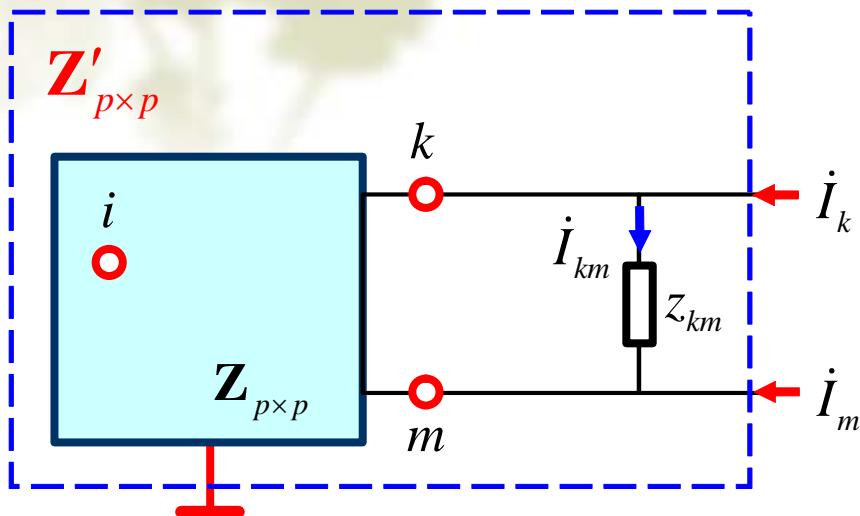
$$\dot{V}_i = \sum_{j=1}^p Z_{ij} \dot{I}_j - (Z_{ik} - Z_{im}) \dot{I}_{km}$$

$$\dot{I}_{km} = \frac{1}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})} \sum_{j=1}^p (Z_{kj} - Z_{mj}) \dot{I}_j$$

$$\dot{V}_i = \sum_{j=1}^p Z_{ij} \dot{I}_j - \frac{(Z_{ik} - Z_{im})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})} \sum_{j=1}^p (Z_{kj} - Z_{mj}) \dot{I}_j$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加连支



$$Z'_{ij} = Z_{ij} - \frac{(Z_{ik} - Z_{im})(Z_{kj} - Z_{mj})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})} \quad (i, j = 1, 2, \dots, p)$$

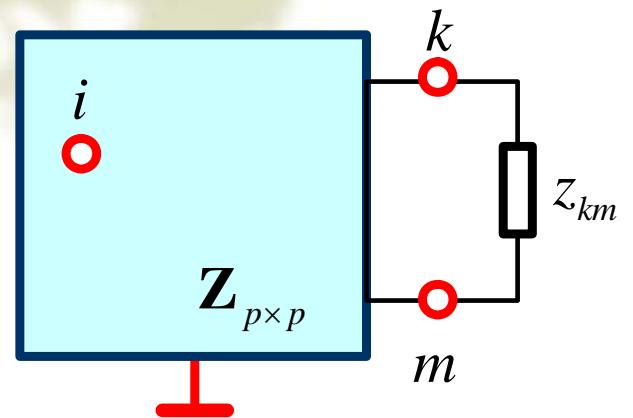
$$\dot{V}_i = \sum_{j=1}^p Z_{ij} \dot{I}_j - \frac{(Z_{ik} - Z_{im})(Z_{kj} - Z_{mj})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})} \sum_{j=1}^p (Z_{kj} - Z_{mj}) \dot{I}_j$$

$$\dot{V}_i = \sum_{j=1}^p Z'_{ij} \dot{I}_j$$

$$\dot{V}_i = \sum_{j=1}^p \left[Z_{ij} - \frac{(Z_{ik} - Z_{im})(Z_{kj} - Z_{mj})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})} \right] \dot{I}_j$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加连支



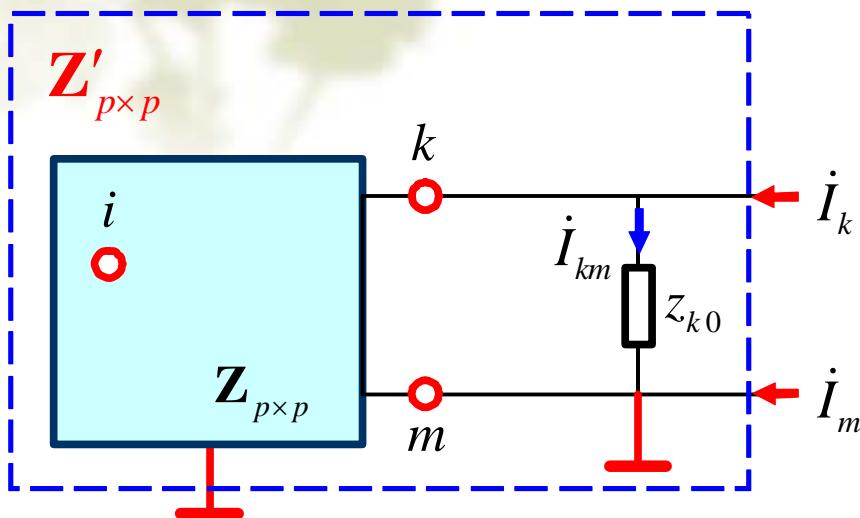
$\boxed{\mathbf{Z}_{p \times p}}$ $\xrightarrow{\hspace{1cm}}$ $\boxed{\mathbf{Z}'_{p \times p}}$

$$\left[\begin{array}{cccc|c} Z'_{11} & \cdots & Z'_{1m} & \cdots & Z'_{1k} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z'_{m1} & \cdots & Z'_{mm} & \cdots & Z'_{mk} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z'_{k1} & \cdots & Z'_{km} & \cdots & Z'_{kk} \\ \hline \vdots & \cdots & \vdots & \cdots & \vdots \end{array} \right]$$

$$Z'_{ij} = Z_{ij} - \frac{(Z_{ik} - Z_{im})(Z_{kj} - Z_{mj})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})} \quad (i, j = 1, 2, \dots, p)$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加接地连支



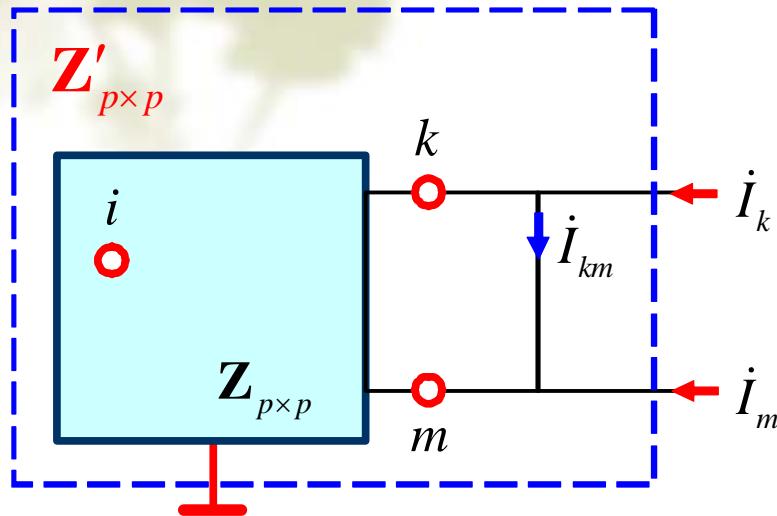
$$Z'_{ij} = Z_{ij} - \frac{(Z_{ik} - Z_{im})(Z_{kj} - Z_{mj})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})} \quad (i, j = 1, 2, \dots, p)$$

$$Z_{im} = Z_{mj} = Z_{km} = Z_{mm} = 0$$

$$Z'_{ij} = Z_{ij} - \frac{Z_{ik} Z_{kj}}{Z_{kk} + z_{k0}}, \quad (i, j = 1, 2, \dots, p)$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加零阻抗连支



$$Z'_{ij} = Z_{ij} - \frac{(Z_{ik} - Z_{im})(Z_{kj} - Z_{mj})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})}$$

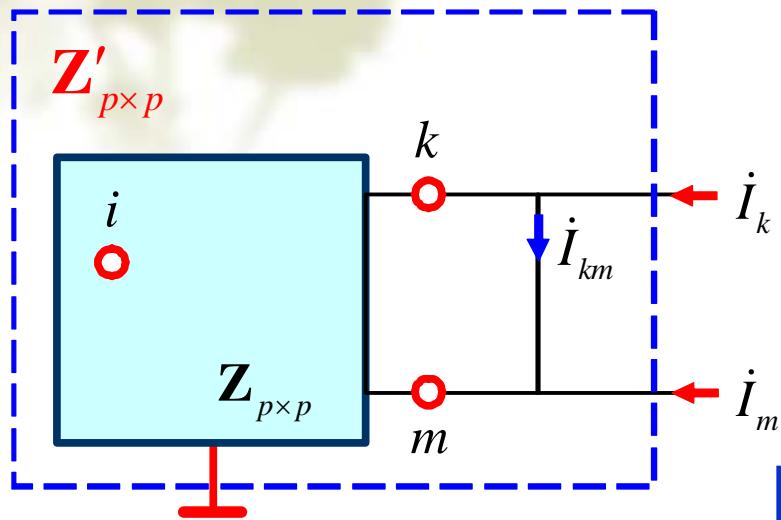
$$Z'_{ik} = Z_{ik} - \frac{(Z_{ik} - Z_{im})(Z_{kk} - Z_{mk})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})}$$

$$Z'_{im} = Z_{im} - \frac{(Z_{ik} - Z_{im})(Z_{km} - Z_{mm})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})}$$

$$Z'_{ik} - Z'_{im} = Z_{ik} - Z_{im} - \frac{(Z_{ik} - Z_{im})(Z_{kk} - Z_{mk})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})} + \frac{(Z_{ik} - Z_{im})(Z_{km} - Z_{mm})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})}$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加零阻抗连支



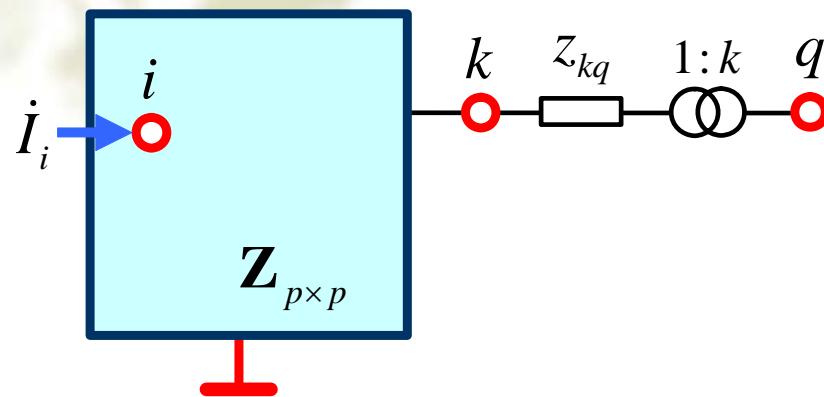
$z_{km} = 0$, 相当于 k 、 m 节点合并,
则有 $Z'_{ik} - Z'_{im} = 0$, 即第 k 列和
第 m 列元素完全相等

$$Z'_{ik} - Z'_{im} = (Z_{ik} - Z_{im}) \left[1 - \frac{(Z_{kk} - Z_{mk}) - (Z_{km} - Z_{mm})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})} \right]$$

$$Z'_{ik} - Z'_{im} = Z_{ik} - Z_{im} - \frac{(Z_{ik} - Z_{im})(Z_{kk} - Z_{mk})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})} + \frac{(Z_{ik} - Z_{im})(Z_{km} - Z_{mm})}{(Z_{kk} + Z_{mm} - 2Z_{km} + z_{km})}$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加变压器树支



i 节点单独注入电流 \dot{I}_i

$$\dot{V}_k = Z_{ki} \dot{I}_i$$

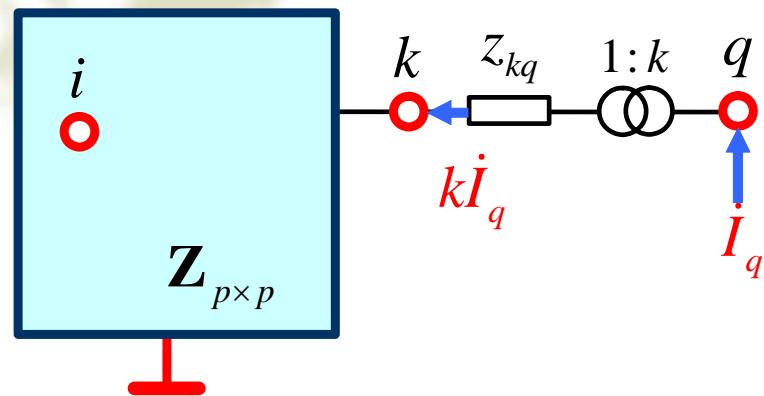
$$\dot{V}_q = Z_{qi} \dot{I}_i = k \dot{V}_k = k Z_{ki} \dot{I}_i$$

$$\begin{bmatrix} Z_{11} & \cdots & Z_{1i} & \cdots & Z_{1p} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z_{k1} & \cdots & Z_{kk} & \cdots & Z_{kp} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z_{p1} & \cdots & Z_{pk} & \cdots & Z_{pp} \\ \hline Z_{q1} & \cdots & Z_{qk} & \cdots & Z_{qp} \end{bmatrix} \quad \begin{matrix} Z_{1q} \\ \vdots \\ Z_{kq} \\ \vdots \\ Z_{pq} \\ Z_{qq} \end{matrix}$$

$$Z_{qi} = k Z_{ki}$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加变压器树支



q 节点单独注入电流 \dot{I}_q

$$\begin{bmatrix} Z_{11} & \cdots & Z_{1i} & \cdots & Z_{1p} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z_{k1} & \cdots & Z_{kk} & \cdots & Z_{kp} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z_{p1} & \cdots & Z_{pk} & \cdots & Z_{pp} \\ \hline Z_{q1} & \cdots & Z_{qk} & \cdots & Z_{qp} \end{bmatrix} \quad \begin{bmatrix} Z_{1q} \\ \vdots \\ Z_{kq} \\ \vdots \\ Z_{pq} \\ Z_{qq} \end{bmatrix}$$

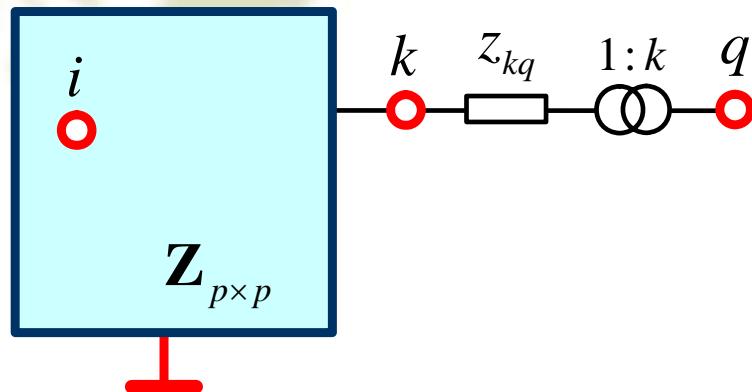
$$\dot{V}_i = Z_{iq} \dot{I}_q = k Z_{ik} \dot{I}_q \quad \rightarrow$$

$$Z_{iq} = k Z_{ik}$$

$$\dot{V}_q = k \left(\dot{V}_k + z_{kq} k \dot{I}_q \right) = k^2 \left(Z_{kk} + z_{kq} \right) \dot{I}_q = Z_{qq} \dot{I}_q$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加变压器树支



Z阵增加一行一列

Z阵原有元素不变

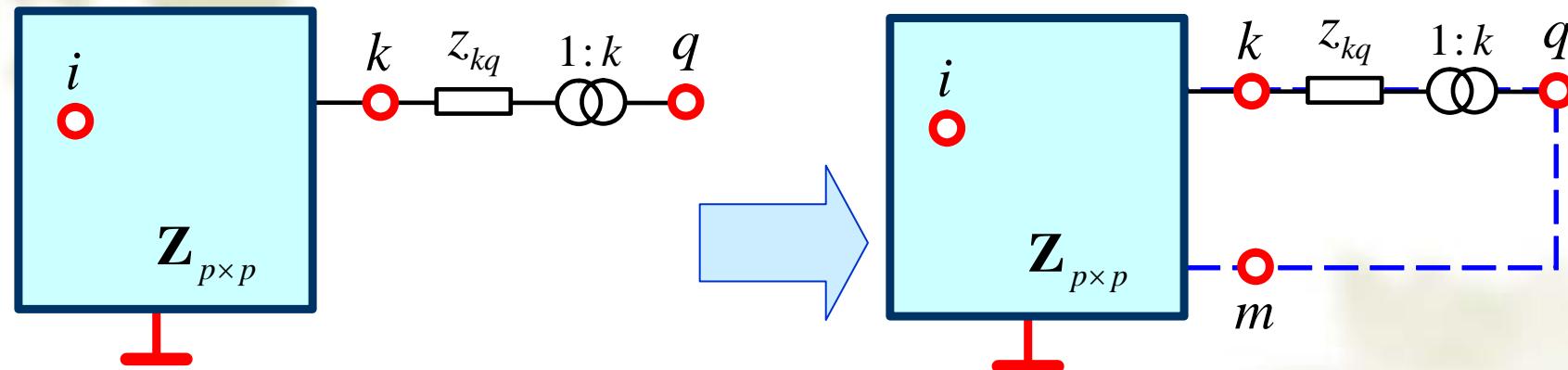
$$\begin{bmatrix} Z_{11} & \cdots & Z_{1i} & \cdots & Z_{1p} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z_{k1} & \cdots & Z_{kk} & \cdots & Z_{kp} \\ \vdots & \cdots & \vdots & \cdots & \vdots \\ Z_{p1} & \cdots & Z_{pk} & \cdots & Z_{pp} \\ \hline Z_{q1} & \cdots & Z_{qk} & \cdots & Z_{qp} \end{bmatrix} \quad \begin{matrix} Z_{1q} \\ \vdots \\ Z_{kq} \\ \vdots \\ Z_{pq} \\ Z_{qq} \end{matrix}$$

$$Z_{iq} = Z_{qi} = kZ_{ki}, (i = 1, 2, \dots, p)$$

$$Z_{qq} = k^2 (Z_{kk} + z_{kq})$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加变压器连支



$$Z_{p \times p} \xrightarrow{\quad} Z_{(p+1) \times (p+1)}$$

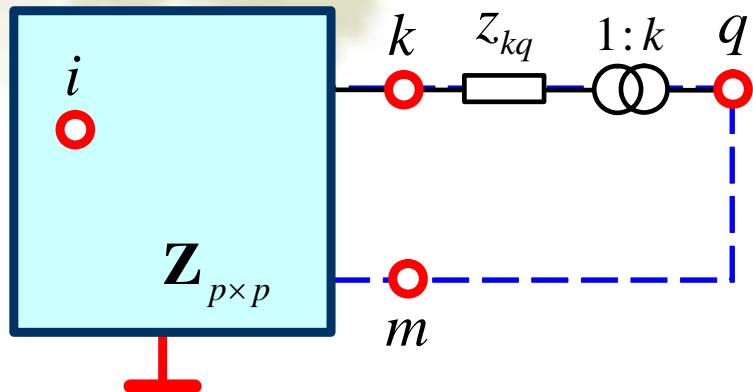
$$Z'_{p \times p} \xleftarrow{\quad} Z'_{(p+1) \times (p+1)}$$

$$\begin{aligned} Z_{iq} &= Z_{qi} = kZ_{ik} \\ Z_{qq} &= k^2 (Z_{kk} + z_{kq}) \end{aligned}$$

$$Z'_{ij} = Z_{ij} - \frac{(Z_{iq} - Z_{im})(Z_{qj} - Z_{mj})}{(Z_{qq} + Z_{mm} - 2Z_{qm})}$$

4-3 节点阻抗矩阵

3. 支路追加法生成Z阵-追加变压器连支



$$Z'_{ij} = Z_{ij} - \frac{(Z_{iq} - Z_{im})(Z_{qj} - Z_{mj})}{(Z_{qq} + Z_{mm} - 2Z_{qm})}$$

$$\mathbf{Z}'_{p \times p}$$

$$Z_{iq} = Z_{qi} = kZ_{ik}, Z_{qq} = k^2(Z_{kk} + z_{kq})$$

$$Z'_{ij} = Z_{ij} - \frac{(kZ_{ik} - Z_{im})(kZ_{kj} - Z_{mj})}{k^2(Z_{kk} + z_{kq}) + Z_{mm} - 2kZ_{mk}}, (i, j = 1, 2, \dots, p)$$

4-3 节点阻抗矩阵

4. 由线性代数方程 $\mathbf{Y}\mathbf{Z}=\mathbf{I}$ 计算 \mathbf{Z} 阵

$$\begin{bmatrix} Y_{11} & Y_{12} & \cdots & Y_{1n} \\ Y_{21} & Y_{22} & \cdots & Y_{2n} \\ \vdots & \vdots & \cdots & \vdots \\ Y_{n1} & Y_{n2} & \cdots & Y_{nn} \end{bmatrix} \begin{bmatrix} Z_{11} & Z_{12} & \cdots & Z_{1n} \\ Z_{21} & Z_{22} & \cdots & Z_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ Z_{n1} & Z_{n2} & \cdots & Z_{nn} \end{bmatrix} = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}$$

$$\mathbf{Y}[\mathbf{Z}_1 \ \mathbf{Z}_2 \ \cdots \ \mathbf{Z}_n] = [\mathbf{e}_1 \ \mathbf{e}_2 \ \cdots \ \mathbf{e}_n]$$

$$\mathbf{Z}_j = [Z_{1j} \ Z_{2j} \ \cdots \ Z_{nj}]^T$$

$$\mathbf{Y}\mathbf{Z}_j = \mathbf{e}_j, (j=1, 2, \dots, n)$$

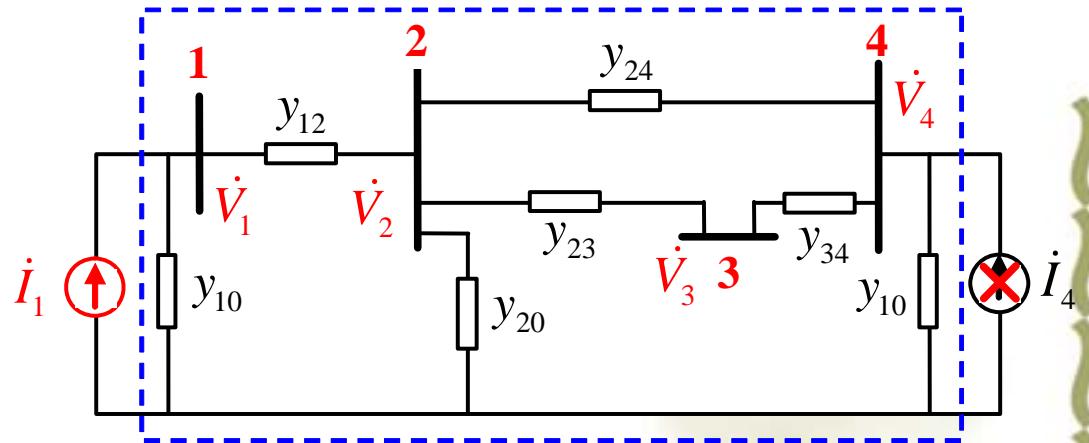
$$\mathbf{e}_j = [0 \ \cdots \ 1 \ \cdots \ 0]^T$$

第 j 列

4-3 节点阻抗矩阵

4. 由线性代数方程 $YZ=I$ 计算 Z 阵

$$\begin{bmatrix} Y_{11} & \cdots & Y_{1j} & \cdots & Y_{1n} \\ \vdots & & \vdots & & \vdots \\ Y_{j1} & \cdots & Y_{jj} & \cdots & Y_{jn} \\ \vdots & & \vdots & & \vdots \\ Y_{n1} & \cdots & Y_{nj} & \cdots & Y_{nn} \end{bmatrix} \begin{bmatrix} Z_{1j} \\ \vdots \\ Z_{jj} \\ \vdots \\ Z_{nj} \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix}$$



$$YZ_j = e_j$$

$$Y\dot{V} = \dot{I}$$

$$\begin{aligned} \dot{I}_i &= 0, \\ \dot{I}_j &= 1, \\ (i &\neq j) \end{aligned}$$

$$\begin{aligned} \dot{V}_j &= Z_{jj} \dot{I}_j = Z_{jj} \\ \dot{V}_i &= Z_{ij} \dot{I}_j = Z_{ij} \end{aligned}$$

方程的物理意义

4-3 节点阻抗矩阵

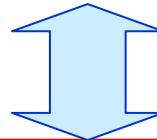
4. 由线性代数方程 $YZ=I$ 计算 Z 阵

$$\begin{bmatrix} Y_{11} & \cdots & Y_{1j} & \cdots & Y_{1n} \\ \vdots & & \vdots & & \vdots \\ Y_{j1} & \cdots & Y_{jj} & \cdots & Y_{jn} \\ \vdots & & \vdots & & \vdots \\ Y_{n1} & \cdots & Y_{nj} & \cdots & Y_{nn} \end{bmatrix} \begin{bmatrix} Z_{1j} \\ \vdots \\ Z_{jj} \\ \vdots \\ Z_{nj} \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix}$$

$$YZ_j = e_j$$

$$LDUZ_j = e_j$$

$$Y = LDU$$



$$\begin{bmatrix} Y_{11} & \cdots & Y_{1j} & \cdots & Y_{1n} \\ \vdots & & \vdots & & \vdots \\ Y_{j1} & \cdots & Y_{jj} & \cdots & Y_{jn} \\ \vdots & & \vdots & & \vdots \\ Y_{n1} & \cdots & Y_{nj} & \cdots & Y_{nn} \end{bmatrix} = \begin{bmatrix} 1 & & & & \\ l_{21} & 1 & & & \\ l_{31} & l_{32} & 1 & & \\ \vdots & \vdots & \vdots & \ddots & \\ l_{n1} & l_{n2} & l_{n3} & \cdots & 1 \end{bmatrix} \begin{bmatrix} d_{11} & & & & \\ & d_{22} & & & \\ & & d_{33} & & \\ & & & \ddots & \\ & & & & d_{nn} \end{bmatrix} \begin{bmatrix} 1 & u_{12} & u_{13} & \cdots & u_{1n} \\ 1 & u_{23} & \cdots & u_{2n} \\ 1 & \cdots & u_{3n} \\ \vdots & & \vdots \\ & & 1 \end{bmatrix}$$

4-3 节点阻抗矩阵

4. 由线性代数方程 $YZ=I$ 计算 Z 阵

$$LDUZ_j = e_j$$

$$LF = e_j$$

$$f_i = \begin{cases} 0 & i < j \\ 1 & i = j \\ -\sum_{k=j}^{i-1} l_{ik} f_k, & i > j \end{cases}$$

$$\begin{bmatrix} 1 & & & & & \\ l_{21} & 1 & & & & \\ l_{31} & l_{32} & 1 & & & \\ \vdots & \vdots & \vdots & \ddots & & \\ l_{j1} & l_{j2} & l_{j3} & \cdots & 1 & \\ \vdots & \vdots & \vdots & & \vdots & \ddots \\ l_{i1} & l_{i2} & l_{i3} & \cdots & l_{ij} & \cdots & 1 \\ \vdots & \vdots & \vdots & & \vdots & & \vdots & \ddots \\ l_{n1} & l_{n2} & l_{n3} & \cdots & l_{nj} & \cdots & l_{ni} & \cdots & 1 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ \vdots \\ f_j \\ f_i \\ \vdots \\ f_n \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ \vdots \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

4-3 节点阻抗矩阵

4. 由线性代数方程 $YZ=I$ 计算 Z 阵

$$LDUZ_j = e_j$$

$$DUZ_j = F$$

$$DH = F$$

$$h_i = \begin{cases} 0 & i < j \\ f_i/d_{ii} & i \geq j \end{cases}$$

$$\begin{bmatrix} d_{11} & & & & & & \\ & d_{22} & & & & & \\ & & d_{33} & & & & \\ & & & \ddots & & & \\ & & & & d_{jj} & & \\ & & & & & \ddots & \\ & & & & & & d_{ii} \\ & & & & & & & \ddots & \\ & & & & & & & & d_{nn} \end{bmatrix} \begin{bmatrix} h_1 \\ h_2 \\ h_3 \\ \vdots \\ h_j \\ \vdots \\ h_i \\ \vdots \\ h_n \end{bmatrix} = \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ \vdots \\ f_j \\ \vdots \\ f_i \\ \vdots \\ f_n \end{bmatrix}$$

4-3 节点阻抗矩阵

4. 由线性代数方程 $YZ=I$ 计算 Z 阵

$$LDUZ_j = e_j$$

$$LF = e_j$$

$$DUZ_j = F$$

$$DH = F$$

$$UZ_j = H$$

$$\begin{bmatrix} 1 & u_{12} & u_{13} & \cdots & u_{1j} & \cdots & u_{1i} & \cdots & u_{1n} \\ & 1 & u_{23} & \cdots & u_{2j} & \cdots & u_{2i} & \cdots & u_{2n} \\ & & 1 & \cdots & u_{3j} & \cdots & u_{3i} & \cdots & u_{3n} \\ & & & \ddots & \vdots & & \vdots & & \vdots \\ & & & & 1 & \cdots & u_{ji} & \cdots & u_{jn} \\ & & & & & \ddots & \vdots & & \vdots \\ & & & & & & 1 & \cdots & u_{in} \\ & & & & & & & \ddots & \vdots \\ & & & & & & & & 1 \end{bmatrix} \begin{bmatrix} Z_{1j} \\ Z_{2j} \\ Z_{3j} \\ \vdots \\ Z_{jj} \\ \vdots \\ Z_{ij} \\ \vdots \\ Z_{nj} \end{bmatrix} = \begin{bmatrix} h_1 \\ h_2 \\ h_3 \\ \vdots \\ h_j \\ \vdots \\ h_i \\ \vdots \\ h_n \end{bmatrix}$$

$$Z_{ij} = h_i - \sum_{k=i+1}^n u_{ik} Z_{kj}, \quad i = n, n-1, \dots, 1$$

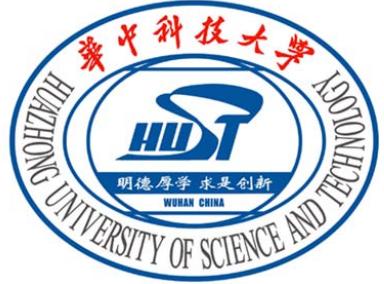
4-3 节点阻抗矩阵

4. 由线性代数方程 $YZ=I$ 计算 Z 阵-因子表

$$\mathbf{L}^T = \mathbf{U}$$

$$l_{ki} = u_{ik}$$

$$\begin{bmatrix} d_{11}^{-1} & u_{12} & u_{13} & \cdots & u_{1j} & \cdots & u_{1i} & \cdots & u_{1n} \\ & d_{22}^{-1} & u_{23} & \cdots & u_{2j} & \cdots & u_{2i} & \cdots & u_{2n} \\ & & d_{33}^{-1} & \cdots & u_{3j} & \cdots & u_{3i} & \cdots & u_{3n} \\ & & & \ddots & \vdots & & \vdots & & \vdots \\ & & & & d_{jj}^{-1} & u_{ji} & \cdots & u_{jn} & \\ & & & & & \ddots & \vdots & & \vdots \\ & & & & & & d_{ii}^{-1} & \cdots & u_{in} \\ & & & & & & & \ddots & \vdots \\ & & & & & & & & d_{nn}^{-1} \end{bmatrix}$$



本章小结

- ❖ Y阵元素的物理意义；Y阵的特点、形成和修改；
- ❖ Z阵元素的物理意义，根据Z阵元素的物理意义形成Z阵的方法；
- ❖ 利用线性代数方程 $YZ_j = e_j$ 计算Z阵的某一列元素；



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习 题

Ex 4-1, 4-2, 4-4



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To Be Continued